

ADS8319 16-Bit, 500-kSPS, Serial Interface, Micropower, Miniature, SAR Analog-to-Digital Converter

1 Features

- 500-kHz Sample Rate
- 16-Bit Resolution
- Zero Latency at Full Speed
- Unipolar, Single-Ended Input Range: 0 V to V_{ref}
- SPI™-Compatible Serial Interface with Daisy-Chain Option
- Excellent Performance:
 - 93.6-dB SNR (Typ) at 10-kHz Input
 - –106-dB THD (Typ) at 10-kHz Input
 - ± 1.5 -LSB (Max) INL
 - ± 1.0 -LSB (Max) DNL
- Low Power Dissipation: 18 mW (Typ) at 500 kSPS
- Power Scales Linearly with Speed: 3.6 mW/100 kSPS
- Power Dissipation During Power-Down State: 0.25 μ W (Typ)
- MSOP-10 and SON-10 Packages

2 Applications

- Battery-Powered Equipment
- Data Acquisition Systems
- Instrumentation and Process Controls
- Medical Electronics
- Optical Networking

3 Description

The ADS8319 is a 16-bit, 500-kSPS, analog-to-digital converter (ADC) that operates with a 2.25-V to 5.5-V external reference. The device includes a capacitor-based, successive-approximation register (SAR) ADC with inherent sample and hold.

The device includes a 50-MHz, SPI-compatible serial interface. The interface is designed to support daisy-chaining or cascading of multiple devices. Furthermore, a *Busy Indicator* makes synchronizing with the digital host easy.

The device unipolar, single-ended input range supports an input swing of 0 V to $+V_{ref}$.

Device operation is optimized for very-low power operation and the power consumption directly scales with speed. This feature makes the device attractive for lower speed applications. The device is available in MSOP-10 and SON-10 packages.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
ADS8319	VSSOP (10)	3.00 mm x 3.00 mm
	SON (10)	3.00 mm x 3.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Simplified Schematic

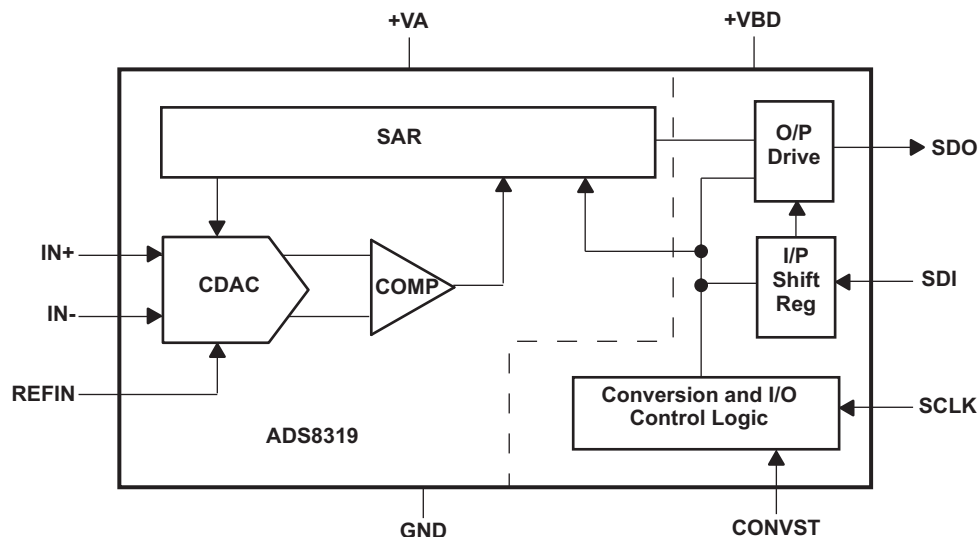


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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

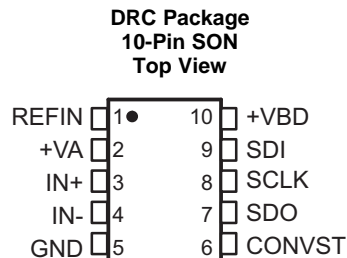
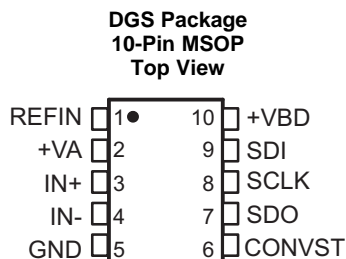
Changes from Revision A (September 2013) to Revision B	Page
• Added <i>Feature Description</i> section, <i>Device Functional Modes</i> section, <i>Device and Documentation Support</i> section, and <i>Mechanical, Packaging, and Orderable Information</i> section	1
• Deleted data from the Device Comparison Table this is repeated in the POA	3
• Changed External Reference Input, V_{ref} parameter maximum specification	5
• Changed V_{DD} to +VA in first sentence fo the <i>Reference</i> section	18
• Changed Figure 51 : added +VBD to device SDI connection	20
• Changed Figure 57 : changed device number for device blocks	24
• Changed Figure 58 : changed SDO #2 trace	24
• Changed Figure 59 : changed device number for device blocks	25
• Changed Figure 60 : changed SDO #2 trace	25

Changes from Original (May 2008) to Revision A	Page
• Changed CBC to CEN in Ordering Information	3
• Changed CBE to CEP in Ordering Information	3

5 Device Comparison Table

DEVICE	MAXIMUM INTEGRAL LINEARITY (LSB)	MAXIMUM DIFFERENTIAL LINEARITY (LSB)	NO MISSING CODES AT RESOLUTION (Bits)
ADS8319I	±2.5	+1.5, -1	16
ADS8319B	±1.5	±1.0	16

6 Pin Configurations and Functions



Pin Functions

PIN		I/O	DESCRIPTION
NO.	NAME		
1	REFIN	Analog input	Reference (positive) input. Decouple to GND with a 0.1-μF bypass capacitor and a 10-μF storage capacitor.
2	+VA	Power	Analog power supply. Decouple to GND.
3	+IN	Analog input	Noninverting analog signal input
4	-IN	Analog input	Inverting analog signal input. Note that this input has a limited range of ±0.1 V and is typically grounded at the input decoupling capacitor.
5	GND	Power	Device ground. Note that this pin is a common ground for both analog power supply (+VA) and digital I/O supply (+VBD).
6	CONVST	Input	Convert input. CONVST also functions as the \overline{CS} input in 3-wire interface mode. See the Description and Timing Requirements sections for more details.
7	SDO	Output	Serial data output
8	SCLK	Input	Serial I/O clock input. Data (on the SDO output) are synchronized with this clock.
9	SDI	Input	Serial data input. The SDI level at the start of a conversion selects the mode of operation (such as \overline{CS} or daisy-chain mode). This pin also serves as the \overline{CS} input in 4-wire interface mode. See the Description and Timing Requirements sections for more details.
10	+VBD	Power	Digital I/O power supply. Decouple to GND.

7 Specifications

7.1 Absolute Maximum Ratings

Over operating free-air temperature range, unless otherwise noted.⁽¹⁾

		MIN	MAX	UNIT
+IN		-0.3	+VA + 0.3	V
			±130	mA
-IN		-0.3	0.3	V
			±130	mA
+VA to AGND		-0.3	7	V
+VBD to BDGND		-0.3	7	V
Digital input voltage to GND		-0.3	+VBD + 0.3	V
Digital output to GND		-0.3	+VBD + 0.3	V
T _A	Operating free-air temperature range	-40	+85	°C
	Junction temperature (T _J max)		+150	°C
MSOP package	Power dissipation	$(T_J \text{ max} - T_A) / \theta_{JA}$		°C
	θ_{JA} thermal impedance		+180	°C/W
Maximum MSOP reflow temperature ⁽²⁾			+260	°C
SON package	Power dissipation	$(T_J \text{ max} - T_A) / \theta_{JA}$		°C
	θ_{JA} thermal impedance		+70	°C/W
Maximum SON reflow temperature ⁽²⁾			+260	°C
T _{stg}	Storage temperature	-65	+150	°C

- (1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) The device is rated to MSL2 260°C, as per the JSTD-020 specification.

7.2 Electrical Characteristics

T_A = -40°C to 85°C, +VA = 5 V, +VBD = 5 V to 2.375 V, V_{ref} = 4 V, and f_{SAMPLE} = 500 kHz, unless otherwise noted.

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
ANALOG INPUT							
Full-scale input span ⁽¹⁾		+IN – (-IN)		0		V _{ref}	V
Operating input range		+IN		-0.1		V _{ref} + 0.1	V
		-IN		-0.1		0.1	
Input capacitance					59		pF
Input leakage current		During acquisition			1000		pA
SYSTEM PERFORMANCE							
Resolution					16		Bits
No missing codes				16			Bits
INL	Integral linearity ⁽²⁾	ADS8319I	At 16-bit level	-2.5	±1.2	2.5	LSB ⁽³⁾
		ADS8319IB		-1.5	±1	1.5	
DNL	Differential linearity	ADS8319I	At 16-bit level	-1	±0.65	1.5	LSB
		ADS8319IB		-1	±0.5	1	
E _O	Offset error ⁽⁴⁾			-1.5	±0.3	1.5	mV
E _G	Gain error			-0.03	±0.0045	0.03	%FSR
CMRR	Common-mode rejection ratio	With common-mode input signal = 200 mV _{PP} at 500 kHz			78		dB
PSRR	Power-supply rejection ratio	At FFF0h output code			80		dB
Transition noise					0.5		LSB

- (1) Ideal input span, does not include gain or offset error.
- (2) This parameter is endpoint INL, not best fit.
- (3) LSB means least significant bit.
- (4) Measured relative to actual measured reference.

Electrical Characteristics (continued)

 $T_A = -40^{\circ}\text{C}$ to 85°C , $+V_A = 5\text{ V}$, $+V_{BD} = 5\text{ V}$ to 2.375 V , $V_{ref} = 4\text{ V}$, and $f_{SAMPLE} = 500\text{ kHz}$, unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SAMPLING DYNAMICS						
t_{CONV}	Conversion time	$+V_{BD} = 5\text{ V}$			1400	ns
		$+V_{BD} = 3\text{ V}$			1400	
	Acquisition time	$+V_{BD} = 5\text{ V}$	600			ns
		$+V_{BD} = 3\text{ V}$	600			
	Maximum throughput rate with or without latency				0.5	MHz
	Aperture delay			2.5		ns
	Aperture jitter, RMS			6		ps
	Step response	Settling to 16-bit accuracy		600		ns
	Overtolerance recovery			600		ns
DYNAMIC CHARACTERISTICS						
THD	Total harmonic distortion ⁽⁵⁾	V_{IN} 0.4 dB below FS at 1 kHz, $V_{ref} = 5\text{ V}$		-111		dB
		V_{IN} 0.4 dB below FS at 10 kHz, $V_{ref} = 5\text{ V}$		-106		
		V_{IN} 0.4 dB below FS at 100 kHz, $V_{ref} = 5\text{ V}$		-89		
SNR	Signal-to-noise ratio	ADS8319IB	V_{IN} 0.4 dB below FS at 1 kHz, $V_{ref} = 5\text{ V}$	92		dB
			V_{IN} 0.4 dB below FS at 1 kHz, $V_{ref} = 5\text{ V}$		93.9	
			V_{IN} 0.4 dB below FS at 10 kHz, $V_{ref} = 5\text{ V}$		93.6	
			V_{IN} 0.4 dB below FS at 100 kHz, $V_{ref} = 5\text{ V}$		92.2	
SINAD	Signal-to-noise + distortion		V_{IN} 0.4 dB below FS at 1 kHz, $V_{ref} = 5\text{ V}$		93.8	dB
			V_{IN} 0.4 dB below FS at 10 kHz, $V_{ref} = 5\text{ V}$		93.4	
			V_{IN} 0.4 dB below FS at 100 kHz, $V_{ref} = 5\text{ V}$		87.4	
SFDR	Spurious-free dynamic range		V_{IN} 0.4 dB below FS at 1 kHz, $V_{ref} = 5\text{ V}$		113	dB
			V_{IN} 0.4 dB below FS at 10 kHz, $V_{ref} = 5\text{ V}$		107	
			V_{IN} 0.4 dB below FS at 100 kHz, $V_{ref} = 5\text{ V}$		90	
	-3-dB small-signal bandwidth			15		MHz
EXTERNAL REFERENCE INPUT						
V_{ref}	Input range		2.25	4.096	$+V_A + 0.1$	V
	Reference input current ⁽⁶⁾	During conversion		250		μA
POWER SUPPLY REQUIREMENTS						
	Power-supply voltage	$+V_{BD}$	2.375	3.3	5.5	V
		$+V_A$	4.5	5	5.5	
	Supply current	$+V_A$	500-kHz sample rate	3.6	4.5	mA
P_{VA}	Power dissipation		$+V_A = 5\text{ V}$, 500-kHz sample rate	18	22.5	mW
$I_{VA_{pd}}$	Device power-down current ⁽⁷⁾		$+V_A = 5\text{ V}$	50	300	nA
LOGIC FAMILY CMOS						
V_{IH}	Logic level		$I_{IH} = 5\text{ }\mu\text{A}$	$+(0.7 \times V_{BD})$	$+V_{BD} + 0.3$	V
V_{IL}			$I_{IL} = 5\text{ }\mu\text{A}$	-0.3	$+(0.3 \times V_{BD})$	
V_{OH}			$I_{OH} = 2\text{ TTL loads}$	$+V_{BD} - 0.3$	$+V_{BD}$	
V_{OL}			$I_{OL} = 2\text{ TTL loads}$	0	0.4	
TEMPERATURE RANGE						
T_A	Operating free-air temperature			-40	+85	$^{\circ}\text{C}$

(5) Calculated on the first nine harmonics of the input frequency.

(6) Can vary by $\pm 20\%$.

(7) The device automatically enters a power-down state at the end of every conversion and remains in a power-down state during the acquisition phase.

7.3 Timing Requirements

All specifications are typical at -40°C to 85°C , $+V_A = 5\text{ V}$, and $+V_{BD} \geq 4.5\text{ V}$, unless otherwise noted.

		REF FIGURE	MIN	TYP	MAX	UNIT
SAMPLING AND CONVERSION RELATED						
t_{acq}	Acquisition time	Figure 50, Figure 52, Figure 53, Figure 55	600			ns
t_{cnv}	Conversion time				1400	ns
t_{cyc}	Time between conversions		2000			ns
t_1	Pulse duration, CONVST high	Figure 50, Figure 52	10			ns
t_6	Pulse duration, CONVST low	Figure 53, Figure 55, Figure 58	20			ns
I/O RELATED						
t_{clk}	SCLK period	Figure 50, Figure 52, Figure 53, Figure 55, Figure 58, Figure 60	20			ns
t_{ckl}	SCLK low time		9			ns
t_{clkh}	SCLK high time		9			ns
t_2	SCLK falling edge to data remains valid		5			ns
t_3	SCLK falling edge to next data valid delay				16	ns
t_{en}	Enable time, CONVST or SDI low to MSB valid	Figure 50, Figure 53			15	ns
t_{dis}	Disable time, CONVST or SDI high or last SCLK falling edge to SDO 3-state ($\overline{\text{CS}}$ mode)	Figure 50, Figure 52, Figure 53, Figure 55			12	ns
t_4	Setup time, SDI valid to CONVST rising edge	Figure 53, Figure 55	5			ns
t_5	Hold time, SDI valid from CONVST rising edge		5			ns
t_7	Setup time, SCLK valid to CONVST rising edge	Figure 58	5			ns
t_8	Hold time, SCLK valid from CONVST rising edge		5			ns

7.4 Timing Requirements

All specifications are typical at -40°C to 85°C , $+V_A = 5\text{ V}$, and $+4.5\text{ V} > +V_{BD} \geq 2.375\text{ V}$, unless otherwise noted.

		REF FIGURE	MIN	TYP	MAX	UNIT
SAMPLING AND CONVERSION RELATED						
t_{acq}	Acquisition time	Figure 50, Figure 52, Figure 53, Figure 55	600			ns
t_{cnv}	Conversion time				1400	ns
t_{cyc}	Time between conversions		2000			ns
t_1	Pulse width CONVST high	Figure 50, Figure 52	10			ns
t_6	Pulse width CONVST low	Figure 53, Figure 55, Figure 58	20			ns
I/O RELATED						
t_{clk}	SCLK period	Figure 50, Figure 52, Figure 53, Figure 55, Figure 58, Figure 60	30			ns
t_{ckl}	SCLK low time		13			ns
t_{clkh}	SCLK high time		13			ns
t_2	SCLK falling edge to data remains valid		5			ns
t_3	SCLK falling edge to next data valid delay				24	ns
t_{en}	CONVST or SDI low to MSB valid	Figure 50, Figure 53			22	ns
t_{dis}	CONVST or SDI high or last SCLK falling edge to SDO 3-state ($\overline{\text{CS}}$ mode)	Figure 50, Figure 52, Figure 53, Figure 55			15	ns
t_4	SDI valid setup time to CONVST rising edge	Figure 53, Figure 55	5			ns
t_5	SDI valid hold time from CONVST rising edge		5			ns
t_7	SCLK valid setup time to CONVST rising edge	Figure 58	5			ns
t_8	SCLK valid hold time from CONVST rising edge		5			ns

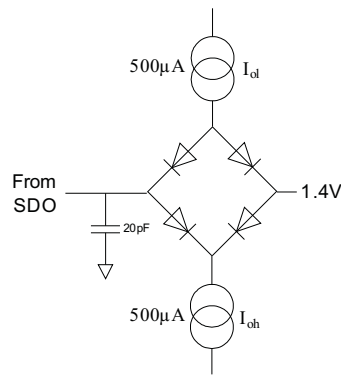


Figure 1. Load Circuit For Digital Interface Timing

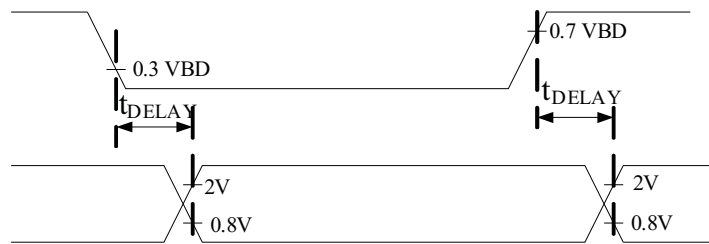


Figure 2. Voltage Levels For Timing

7.5 Typical Characteristics

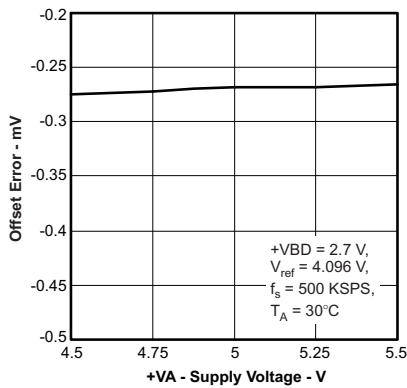


Figure 3. Offset Error vs Supply Voltage

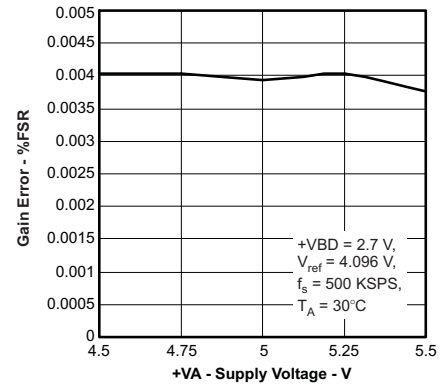


Figure 4. Gain Error vs Supply Voltage

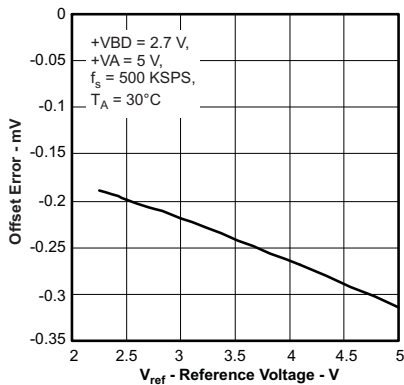


Figure 5. Offset Error vs Reference Voltage

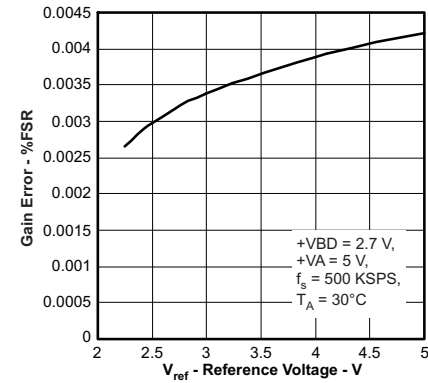


Figure 6. Gain Error vs Reference Voltage

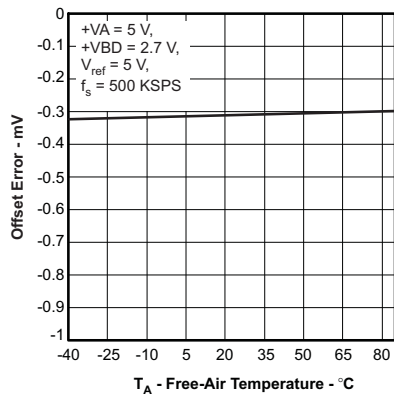


Figure 7. Offset Error vs Free-Air Temperature

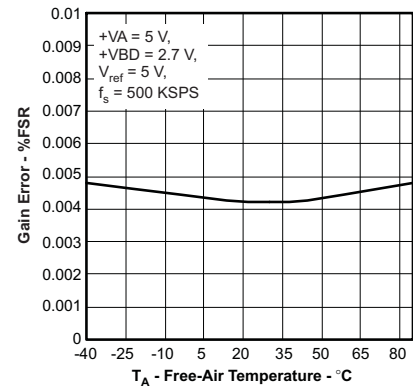


Figure 8. Gain Error vs Free-Air Temperature

Typical Characteristics (continued)

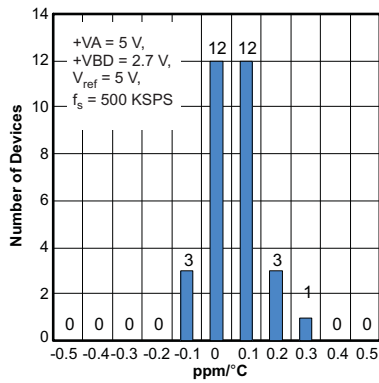


Figure 9. Gain Error Drift Histogram

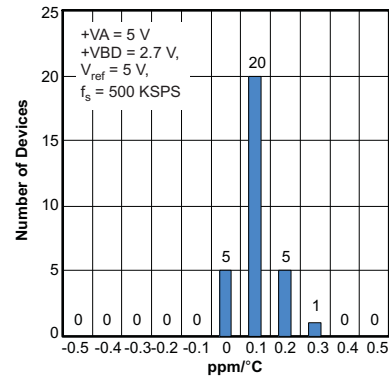


Figure 10. Offset Error Drift Histogram

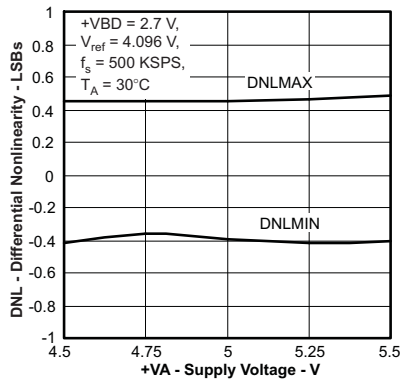


Figure 11. Differential Nonlinearity vs Supply Voltage

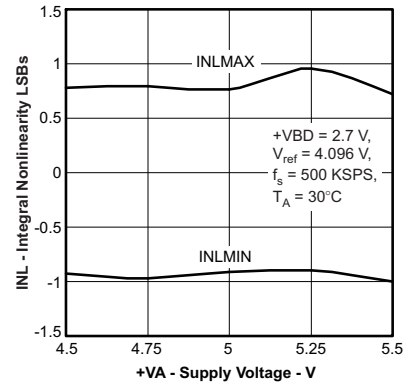


Figure 12. Integral Nonlinearity vs Supply Voltage

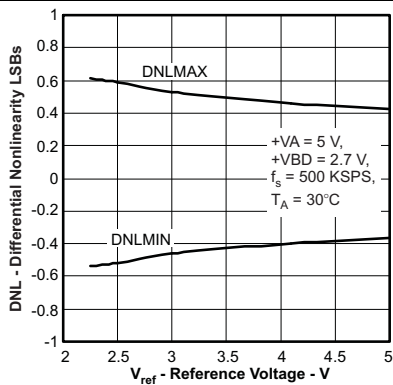


Figure 13. Differential Nonlinearity vs Reference Voltage

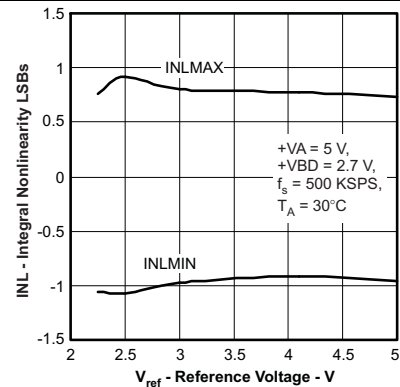


Figure 14. Integral Nonlinearity vs Reference Voltage

Typical Characteristics (continued)

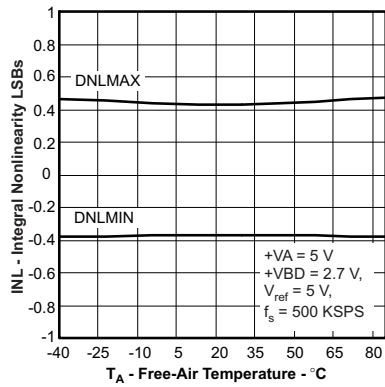


Figure 15. Differential Nonlinearity vs Free-Air Temperature

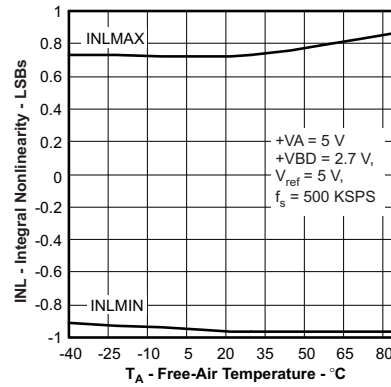


Figure 16. Integral Nonlinearity vs Free-Air Temperature

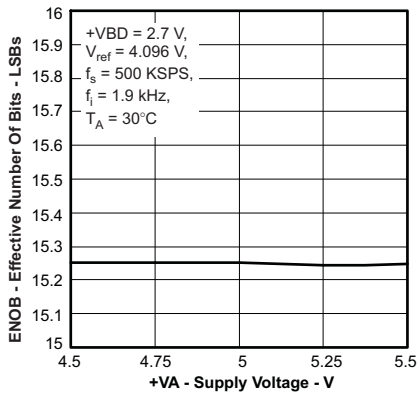


Figure 17. Effective Number of Bits vs Supply Voltage

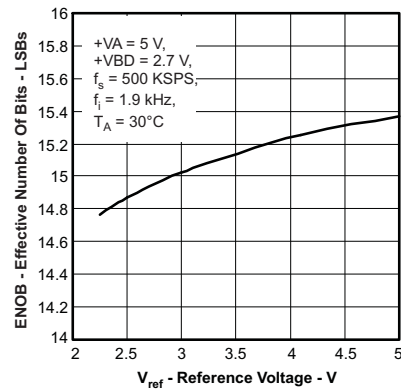


Figure 18. Effective Number of Bits vs Reference Voltage

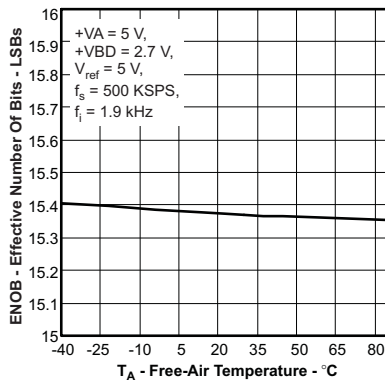


Figure 19. Effective Number of Bits vs Free-Air Temperature

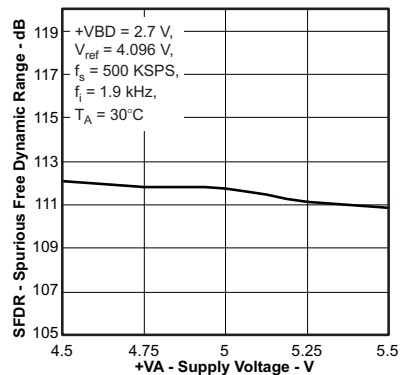


Figure 20. Spurious-Free Dynamic Range vs Supply Voltage

Typical Characteristics (continued)

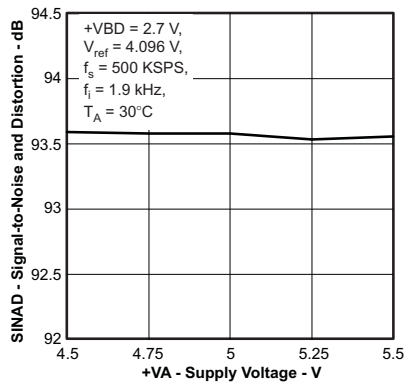


Figure 21. Signal-to-Noise + Distortion vs Supply Voltage

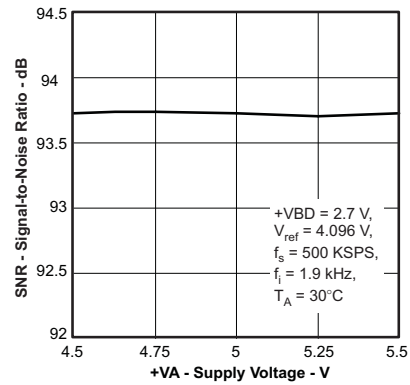


Figure 22. Signal-to-Noise Ratio vs Supply Voltage

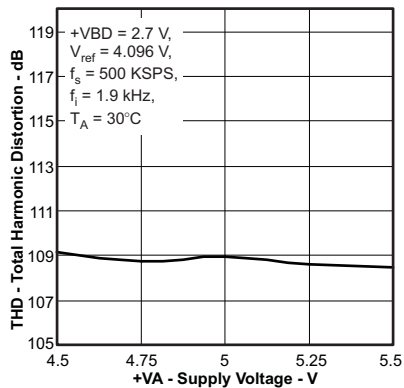


Figure 23. Total Harmonic Distortion vs Supply Voltage

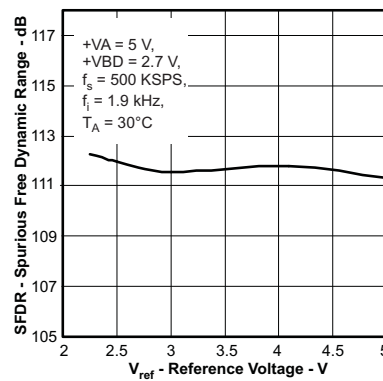


Figure 24. Spurious-Free Dynamic Range vs Reference Voltage

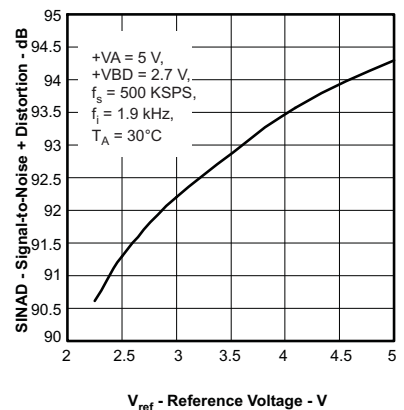


Figure 25. Signal-to-Noise + Distortion vs Reference Voltage

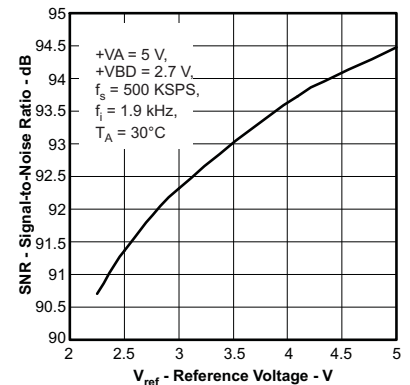


Figure 26. Signal-to-Noise Ratio vs Reference Voltage

Typical Characteristics (continued)

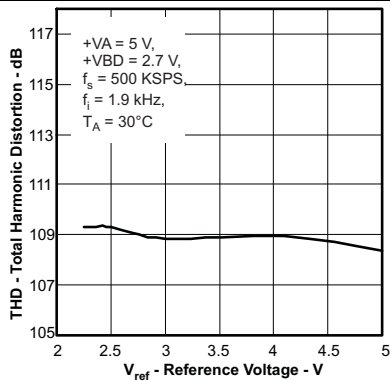


Figure 27. Total Harmonic Distortion vs Reference Voltage

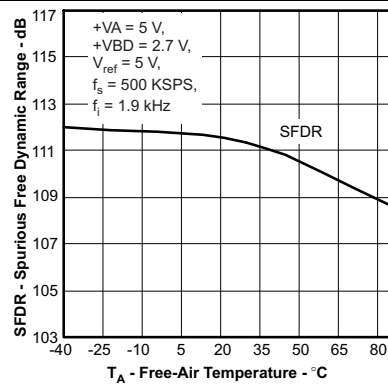


Figure 28. Spurious-Free Dynamic Range vs Free-Air Temperature

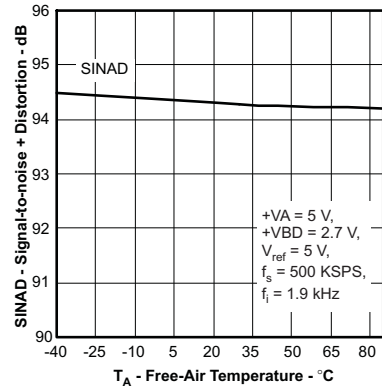


Figure 29. Signal-to-Noise + Distortion vs Free-Air Temperature

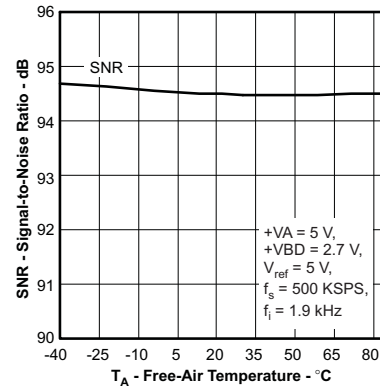


Figure 30. Signal-to-Noise Ratio vs Free-Air Temperature

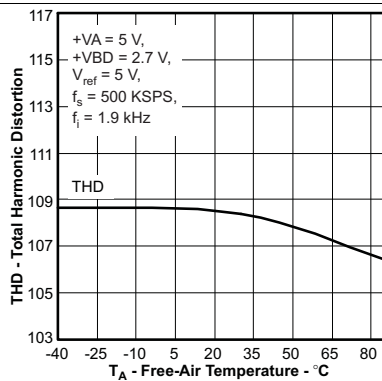


Figure 31. Total Harmonic Distortion vs Free-Air Temperature

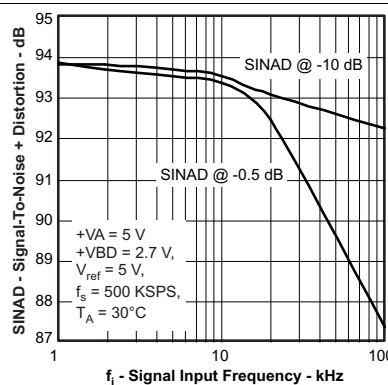


Figure 32. Signal-to-Noise + Distortion vs Signal Input Frequency

Typical Characteristics (continued)

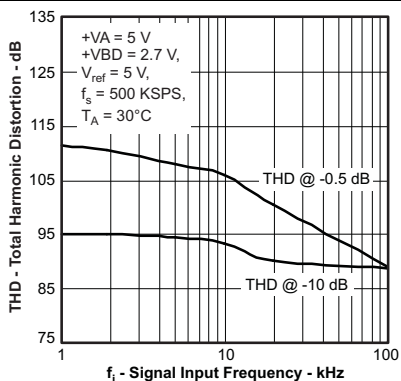


Figure 33. Total Harmonic Distortion vs Signal Input Frequency

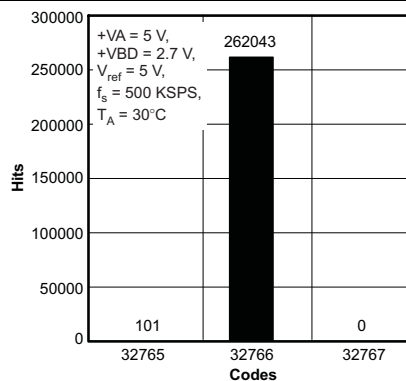


Figure 34. Dc Histogram of ADC Close to Center Code

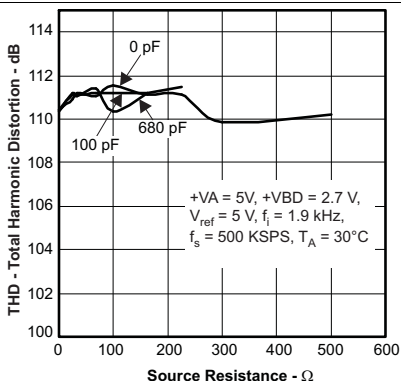


Figure 35. Total Harmonic Distortion vs Source Resistance

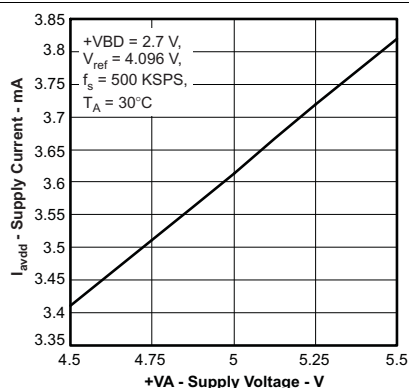


Figure 36. Supply Current vs Supply Voltage

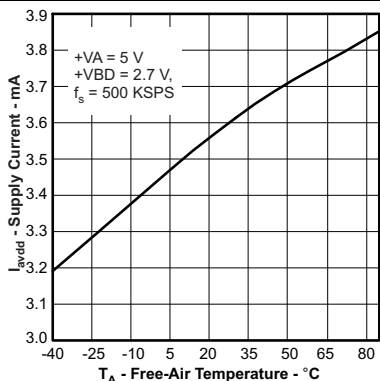


Figure 37. Supply Current vs Free-Air Temperature

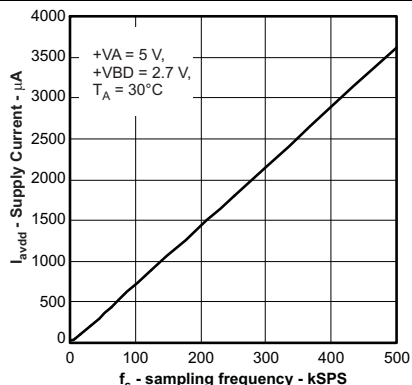


Figure 38. Supply Current vs Sampling Frequency

Typical Characteristics (continued)

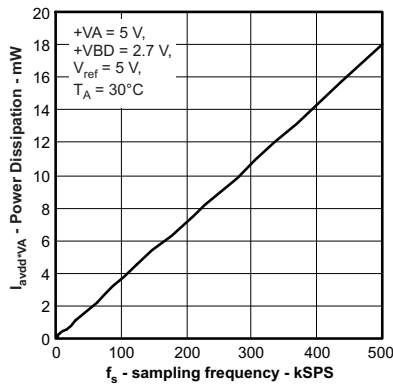


Figure 39. Power Dissipation vs Sampling Frequency

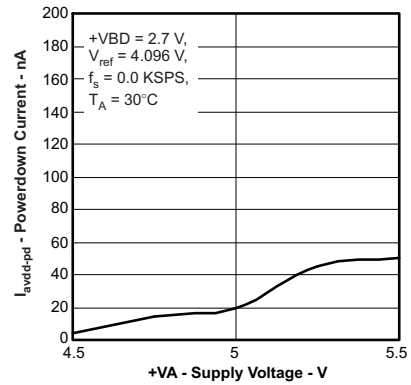


Figure 40. Power-Down Current vs Supply Voltage

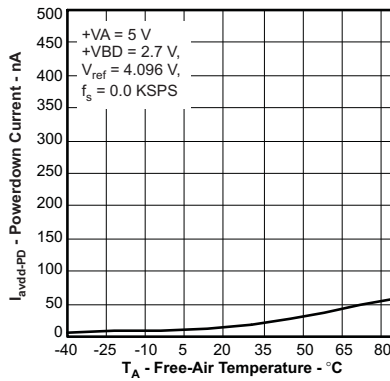


Figure 41. Power-Down Current vs Free-Air Temperature

Typical Characteristics (continued)

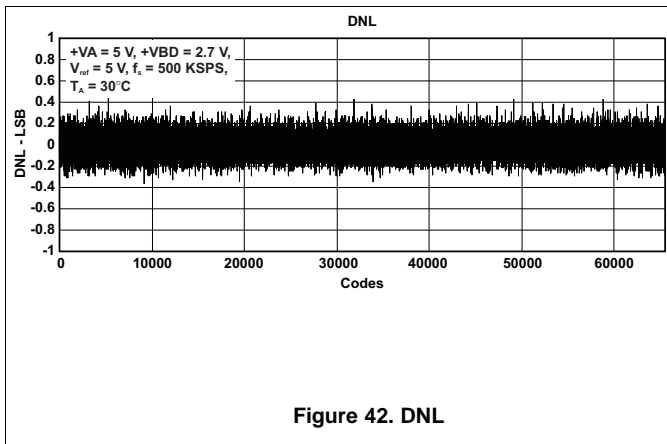


Figure 42. DNL

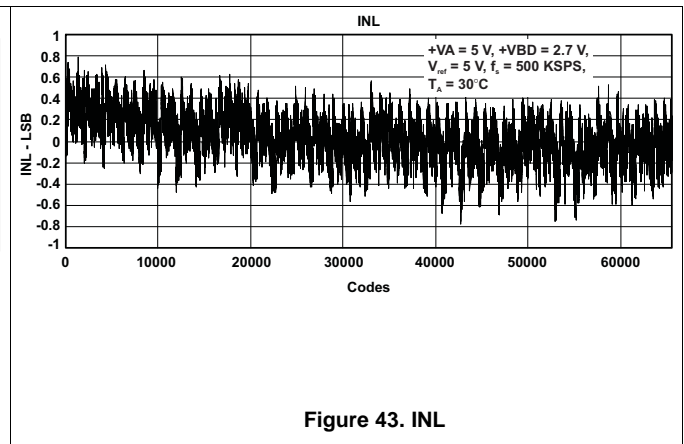


Figure 43. INL

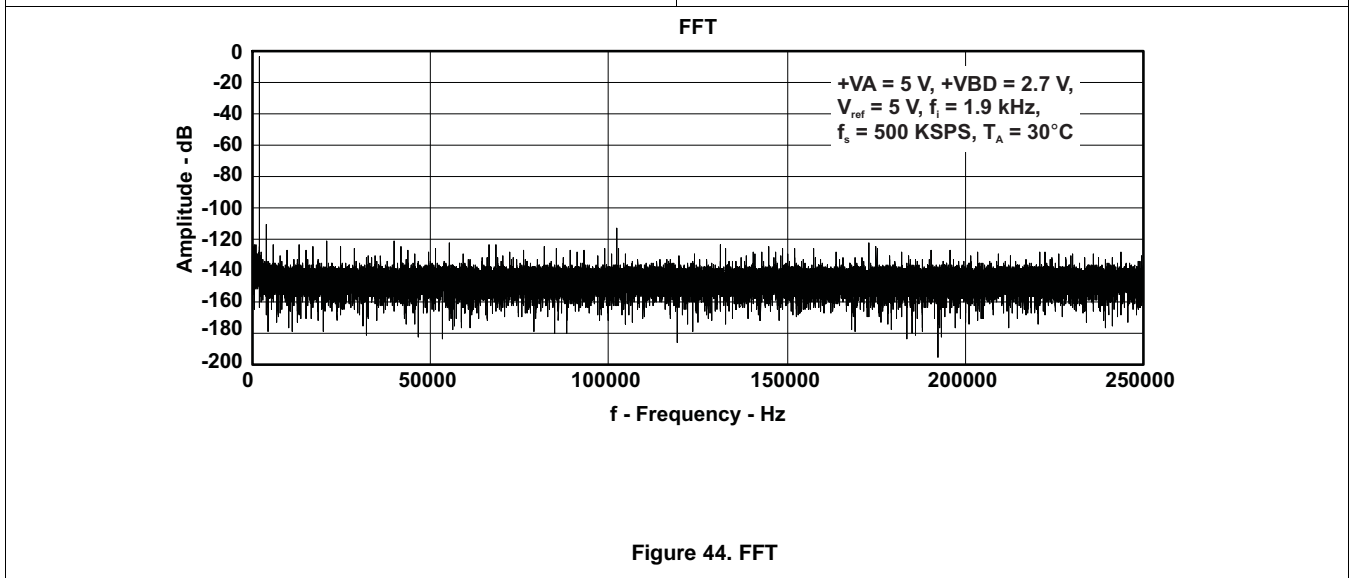


Figure 44. FFT

8 Detailed Description

8.1 Overview

The ADS8319 is a high-speed, low power, successive approximation register (SAR) analog-to-digital converter (ADC) that uses an external reference. The architecture is based on charge redistribution, which inherently includes a sample/hold function.

The ADS8319 is a single channel device. The analog input is provided to two input pins: +IN and -IN where -IN is a pseudo differential input and it has a limited range of ± 0.1 V. When a conversion is initiated, the differential input on these pins is sampled on the internal capacitor array. While a conversion is in progress, both +IN and -IN inputs are disconnected from any internal function.

The ADS8319 has an internal clock that is used to run the conversion, and hence the conversion requires a fixed amount of time. After a conversion is completed, the device reconnects the sampling capacitors to the +IN and -IN pins, and the device is in the acquisition phase. During this phase the device is powered down and conversion data can be read.

The device digital output is available in SPI compatible format. It easily interfaces with microprocessors, DSPs, or FPGAs.

This is a low pin count device; however, it offers six different options for the interface. They can be grossly classified as *CS mode* (3- or 4-wire interface) and *daisy chain mode*. In both modes it can either be with or without a *busy indicator*, where the busy indicator is a bit preceding the 16-bit serial data.

The *3-wire interface CS mode* is useful for applications which need galvanic isolation on-board, where as *4-wire interface CS mode* makes it easy to control an individual device while having multiple devices on-board. The *daisy chain mode* is provided to hook multiple devices in a chain like a shift register and is useful to reduce component count and the number of signal traces on the board.

8.2 Feature Description

8.2.1 Analog Input

When the converter samples the input, the voltage difference between the +IN and -IN inputs is captured on the internal capacitor array. The voltage on the +IN is limited between GND -0.1 V and $V_{ref} + 0.1$ V and on -IN is limited between GND -0.1 to GND $+0.1$ V; where as the differential signal range is $[(+IN) - (-IN)]$. This allows the input to reject small signals which are common to both the +IN and -IN inputs.

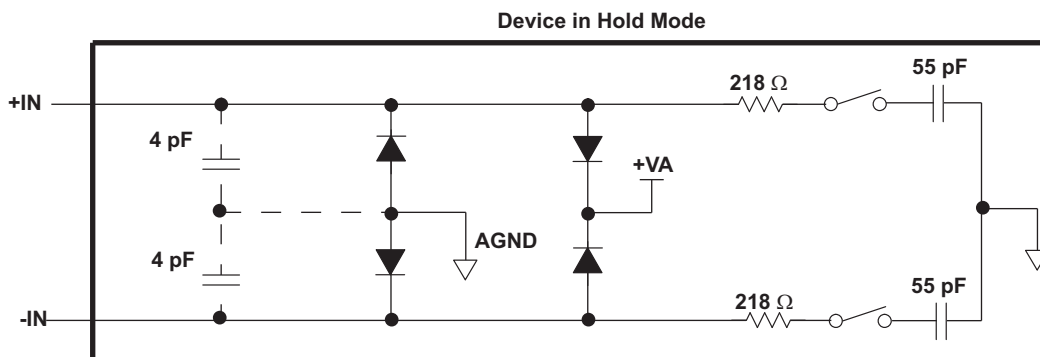


Figure 45. Input Equivalent Circuit

The (peak) input current through the analog inputs depends upon a number of factors: sample rate, input voltage, and source impedance. The current into the ADS8319 charges the internal capacitor array during the sample period. After this capacitance has been fully charged, there is no further input current. The source of the analog input voltage must be able to charge the input capacitance (59 pF) to a 18-bit settling level within the minimum acquisition time. When the converter goes into hold mode, the input impedance is greater than 1 G Ω .

Care must be taken regarding the absolute analog input voltage. To maintain linearity of the converter, the +IN and -IN inputs and the span (+IN – (-IN)) should be within the limits specified. Outside of these ranges, converter linearity may not meet specifications.

Feature Description (continued)

Care should be taken to ensure that the output impedance of the sources driving the +IN and –IN inputs are matched. If this is not observed, the two inputs could have different settling times. This may result in an offset error, gain error, and linearity error which change with temperature and input voltage. Typically the –IN input is grounded at the input decoupling capacitor.

8.2.2 Driver Amplifier Choice

The analog input to the converter needs to be driven with a low noise, op-amp like the THS4031, OPA211. An RC filter is recommended at the input pins to low-pass filter the noise from the source. A resistor of 5Ω and a capacitor of 1nF is recommended. The input to the converter is a unipolar input voltage in the range 0 V to V_{ref} . The minimum –3dB bandwidth of the driving operational amplifier can be calculated as:

$$f_{3db} = (\ln(2) \times (n+2)) / (2\pi \times t_{ACQ})$$

where n is equal to 16, the resolution of the ADC (in the case of the ADS8319). When $t_{ACQ} = 600$ ns (minimum acquisition time), the minimum bandwidth of the driving circuit is ~3 MHz (including RC following the driver OPA). The bandwidth can be relaxed if the acquisition time is increased by the application.

Typically a low noise OPA with ten times or higher bandwidth is selected. The driving circuit bandwidth is adjusted (to the required value) with a RC following the OPA. The OPA211 or THS4031 from Texas Instruments is recommended for driving high-resolution high-speed ADCs.

8.2.3 Driver Amplifier Configurations

It is better to use a unity gain, noninverting buffer configuration. As explained before a RC following the OPA limits the input circuit bandwidth just enough for 16-bit settling. Note higher bandwidth reduces the settling time (beyond what is needed) but increases the noise in the ADC sampled signal, and hence the ADC output.

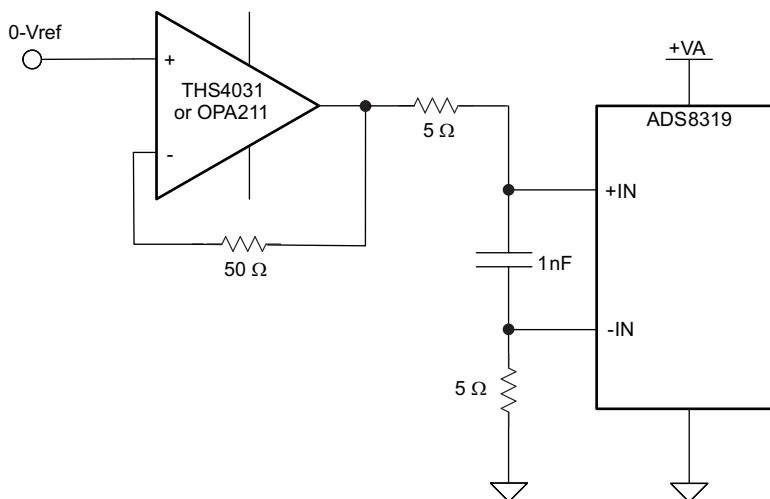


Figure 46. Input Drive Configuration

Feature Description (continued)

8.2.4 Reference

The ADS8319 can operate with an external reference with a range from 2.25 V to +VA + 0.1 V. A clean, low noise, well-decoupled reference voltage on this pin is required to ensure good performance of the converter. A low noise band-gap reference like the REF5040, REF5050 can be used to drive this pin. A ceramic decoupling capacitor is required between the REF+ and GND pins of the converter, as shown in Figure 47. The capacitor should be placed as close as possible to the pins of the device.

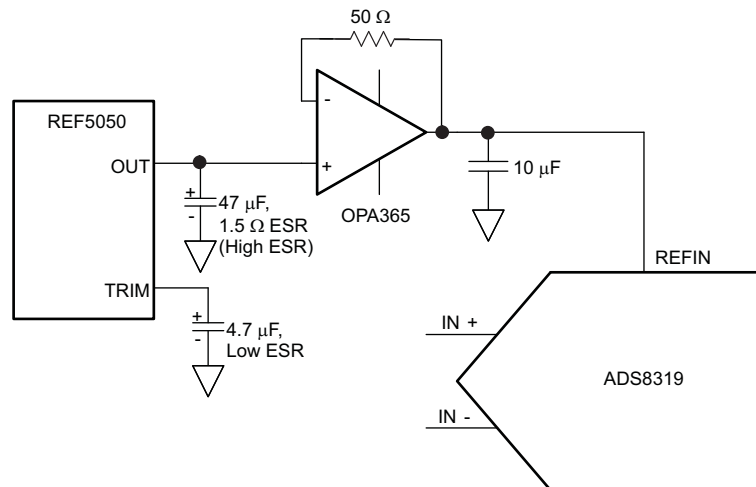


Figure 47. External Reference Driving Circuit

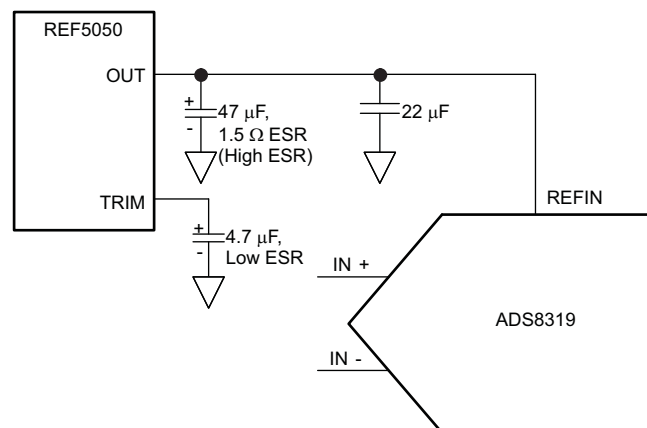


Figure 48. Direct External Reference Driving Circuit

8.2.5 Power Saving

The ADS8319 has an auto power-down feature. The device powers down at the end of every conversion. The input signal is acquired on sampling capacitors while the device is in the power-down state, and at the same time the conversion results are available for reading. The device powers up by itself on the start of the conversion. As discussed before, the conversion runs on an internal clock and takes a fixed time. As a result, device power consumption is directly proportional to the speed of operation.

Feature Description (continued)

8.2.6 Digital Output

As discussed in the [Description](#) and [Timing Requirements](#) sections, the device digital output is SPI compatible. [Table 1](#) lists the output codes corresponding to various analog input voltages.

Table 1. Output Codes

DESCRIPTION	ANALOG VALUE (V)	DIGITAL OUTPUT STRAIGHT BINARY	
		BINARY CODE	HEX CODE
Full-scale range	V_{ref}		
Least significant bit (LSB)	$V_{ref}/65536$		
Positive full scale	$+V_{ref} - 1 \text{ LSB}$	1111 1111 1111 1111	FFFF
Midscale	$V_{ref}/2$	1000 0000 0000 0000	8000
Midscale – 1 LSB	$V_{ref}/2 - 1 \text{ LSB}$	0111 1111 1111 1111	7FFF
Zero	0	0000 0000 0000 0000	0000

8.2.7 SCLK Input

The device uses SCLK for serial data output. Data is read after the conversion is over and the device is in the acquisition phase. It is possible to use a free running SCLK for the device, but it is recommended to stop the clock during a conversion, as the clock edges can couple with the internal analog circuit and can affect conversion results.

8.3 Device Functional Modes

8.3.1 \overline{CS} Mode

\overline{CS} Mode is selected if SDI is high at the rising edge of CONVST. As indicated before there are four different interface options available in this mode, namely *3-wire \overline{CS} mode without busy indicator*, *3-wire \overline{CS} mode with busy indicator*, *4-wire \overline{CS} mode without busy indicator*, *4-wire \overline{CS} mode with busy indicator*. The following section discusses these interface options in detail.

8.3.1.1 3-Wire \overline{CS} Mode Without Busy Indicator

The three wire interface option in \overline{CS} mode is selected if SDI is tied to +VBD, as shown in [Figure 49](#). In the three wire interface option, CONVST acts like \overline{CS} . The device samples the input signal and enters the conversion phase on the rising edge of CONVST, at the same time SDO goes to 3-state; see [Figure 50](#). Conversion is done with the internal clock and it continues irrespective of the state of CONVST. As a result it is possible to bring CONVST (acting as \overline{CS}) low after the start of the conversion to select other devices on the board. But it is absolutely necessary that CONVST is high again before the minimum conversion time (t_{cnv} in timing requirements table) is elapsed. A high level on CONVST at the end of the conversion ensures the device does not generate a busy indicator.

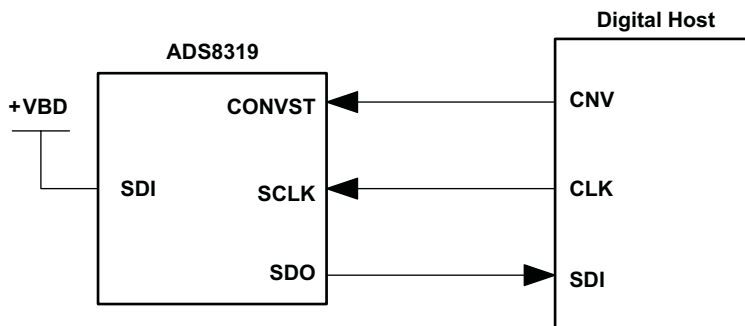


Figure 49. Connection Diagram, 3-Wire \overline{CS} Mode Without Busy Indicator (SDI = 1)

Device Functional Modes (continued)

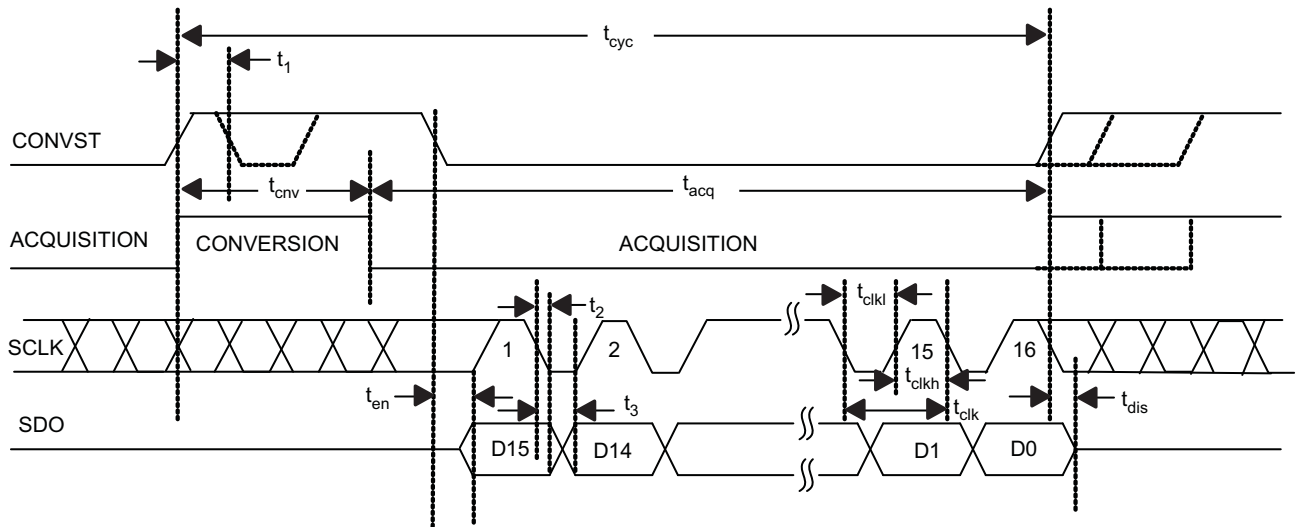


Figure 50. Interface Timing Diagram, 3-Wire \overline{CS} Mode Without Busy Indicator (SDI = 1)

When the conversion is over, the device enters the acquisition phase and powers down. On the falling edge of CONVST, SDO comes out of three state, and the device outputs the MSB of the data. After this, the device outputs the next lower data bits on every falling edge of SCLK. SDO goes to 3-state after the 16th falling edge of SCLK or CONVST high, whichever occurs first. It is necessary that the device sees a minimum of 15 falling edges of SCLK during the low period of CONVST.

8.3.1.2 3-Wire \overline{CS} Mode With Busy Indicator

The three wire interface option in \overline{CS} mode is selected if SDI is tied to +VBD, as shown in Figure 51. In the three wire interface option, CONVST acts like \overline{CS} . The device samples the input signal and enters the conversion phase on the rising edge of CONVST, at the same time SDO goes to 3 state; see Figure 52. Conversion is done with the internal clock and it continues irrespective of the state of CONVST. As a result it is possible to toggle CONVST (acting as \overline{CS}) after the start of the conversion to select other devices on the board. But it is absolutely necessary that CONVST is low again before the minimum conversion time (t_{cnv} in timing requirements table) is elapsed and continues to stay low until the end of maximum conversion time. A low level on the CONVST input at the end of a conversion ensures the device generates a busy indicator.

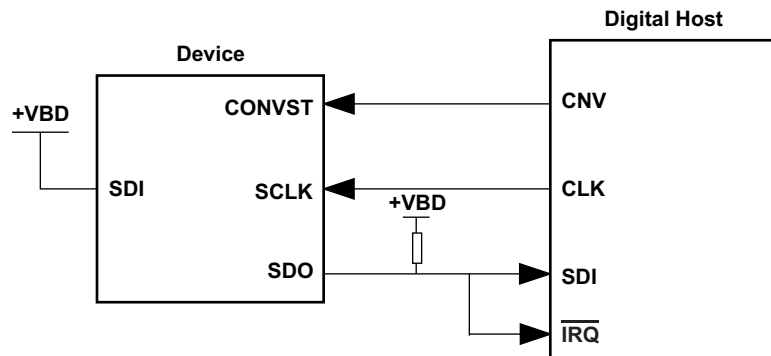


Figure 51. Connection Diagram, 3-Wire \overline{CS} Mode With Busy Indicator

Device Functional Modes (continued)

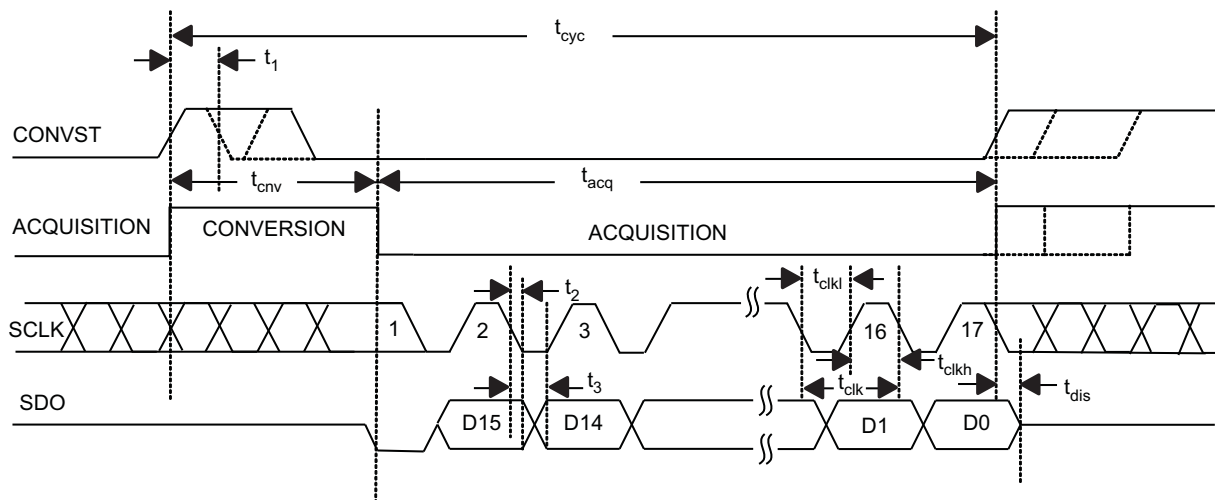


Figure 52. Interface Timing Diagram, 3-Wire \overline{CS} Mode With Busy Indicator (SDI = 1)

When the conversion is over, the device enters the acquisition phase and powers down, and the device forces SDO out of three state and outputs a busy indicator bit (low level). The device outputs the MSB of data on the first falling edge of SCLK after the conversion is over and continues to output the next lower data bits on every subsequent falling edge of SCLK. SDO goes to three state after the 17th falling edge of SCLK or CONVST high, whichever occurs first. It is necessary that the device sees a minimum of 16 falling edges of SCLK during the low period of CONVST.

8.3.1.3 4-Wire \overline{CS} Mode Without Busy Indicator

As mentioned before for selecting \overline{CS} mode it is necessary that SDI is high at the time of the CONVST rising edge. Unlike in *three wire interface option*, SDI is controlled by digital host and acts like \overline{CS} . As shown in Figure 53, SDI goes to a high level before the rising edge of CONVST. The rising edge of CONVST while SDI is high selects \overline{CS} mode, forces SDO to three state, samples the input signal, and the device enters the conversion phase. In the 4 wire interface option CONVST needs to be at a high level from the start of the conversion until all of the data bits are read. Conversion is done with the internal clock and it continues irrespective of the state of SDI. As a result it is possible to bring SDI (acting as \overline{CS}) low to select other devices on the board. But it is absolutely necessary that SDI is high again before the minimum conversion time (t_{cnv} in timing requirements table) is elapsed.

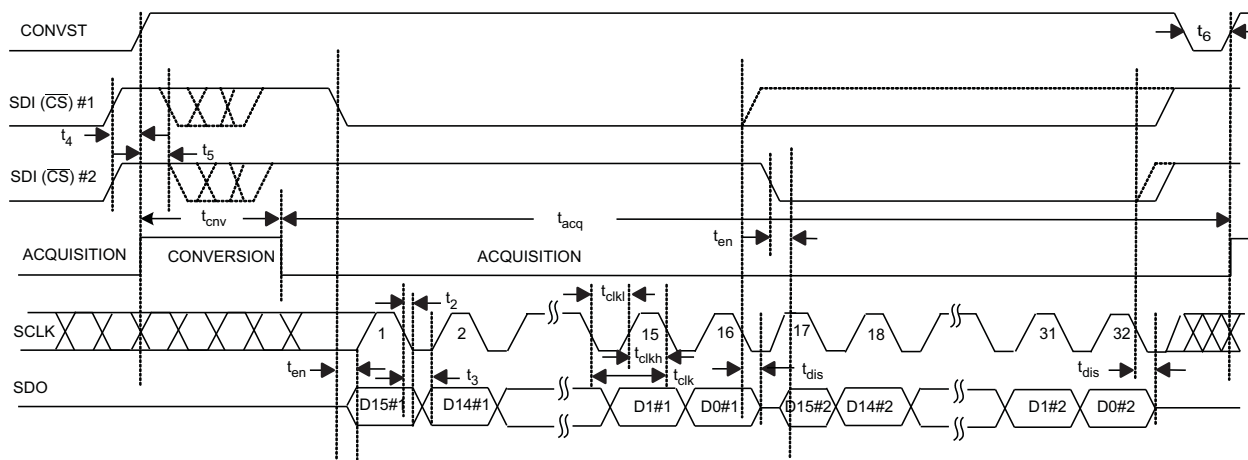


Figure 53. Interface Timing Diagram, 4-Wire \overline{CS} Mode Without Busy Indicator

Device Functional Modes (continued)

When the conversion is over, the device enters the acquisition phase and powers down. SDI falling edge can occur after the maximum conversion time (t_{cnv} in timing requirements table). Note that it is necessary that SDI is high at the end of the conversion, so that the device does not generate a *busy indicator*. The falling edge of SDI brings SDO out of 3-state and the device outputs the MSB of the data. Subsequent to this the device outputs the next lower data bits on every falling edge of SCLK. SDO goes to three state after the 16th falling edge of SCLK or SDI (\overline{CS}) high, whichever occurs first. As shown in Figure 54, it is possible to hook multiple devices on the same data bus. In this case the second device SDI (acting as \overline{CS}) can go low after the first device data is read and device 1 SDO is in three state.

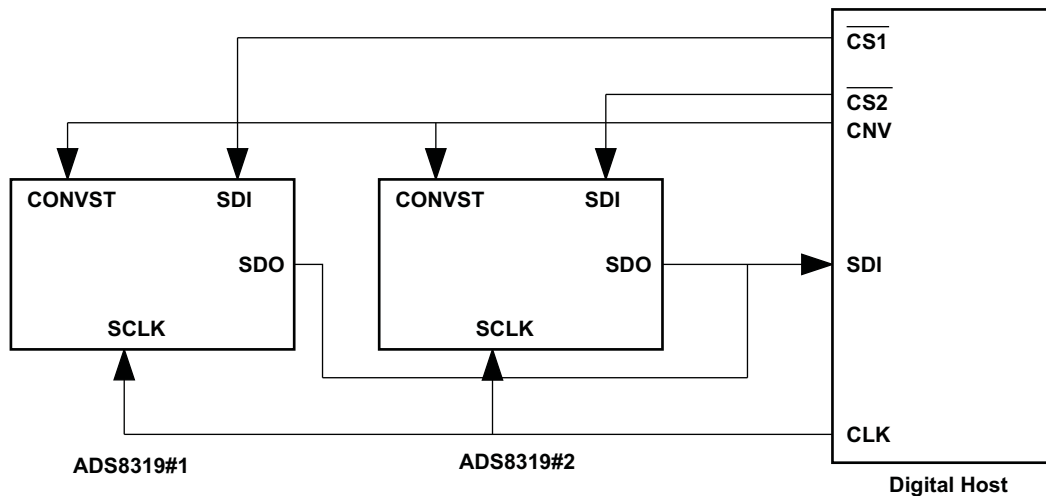


Figure 54. Connection Diagram, 4-Wire \overline{CS} Mode Without Busy Indicator

Care needs to be taken so that CONVST and SDI are not low together at any time during the cycle.

8.3.1.4 4-Wire \overline{CS} Mode With Busy Indicator

As mentioned before for selecting \overline{CS} mode it is necessary that SDI is high at the time of the CONVST rising edge. Unlike in the *three wire interface option*, SDI is controlled by the digital host and acts like \overline{CS} . SDI goes to a high level before the rising edge of CONVST; see Figure 55. The rising edge of CONVST while SDI is high selects \overline{CS} mode, forces SDO to three state, samples the input signal, and the device enters the conversion phase. In the 4 wire interface option CONVST needs to be at a high level from the start of the conversion until all of the data bits are read. Conversion is done with the internal clock and it continues irrespective of the state of SDI. As a result it is possible to toggle SDI (acting as \overline{CS}) to select other devices on the board. But it is absolutely necessary that SDI is low before the minimum conversion time (t_{cnv} in timing requirements table) is elapsed and continues to stay low until the end of the maximum conversion time. A low level on the SDI input at the end of a conversion ensures the device generates a busy indicator.

Device Functional Modes (continued)

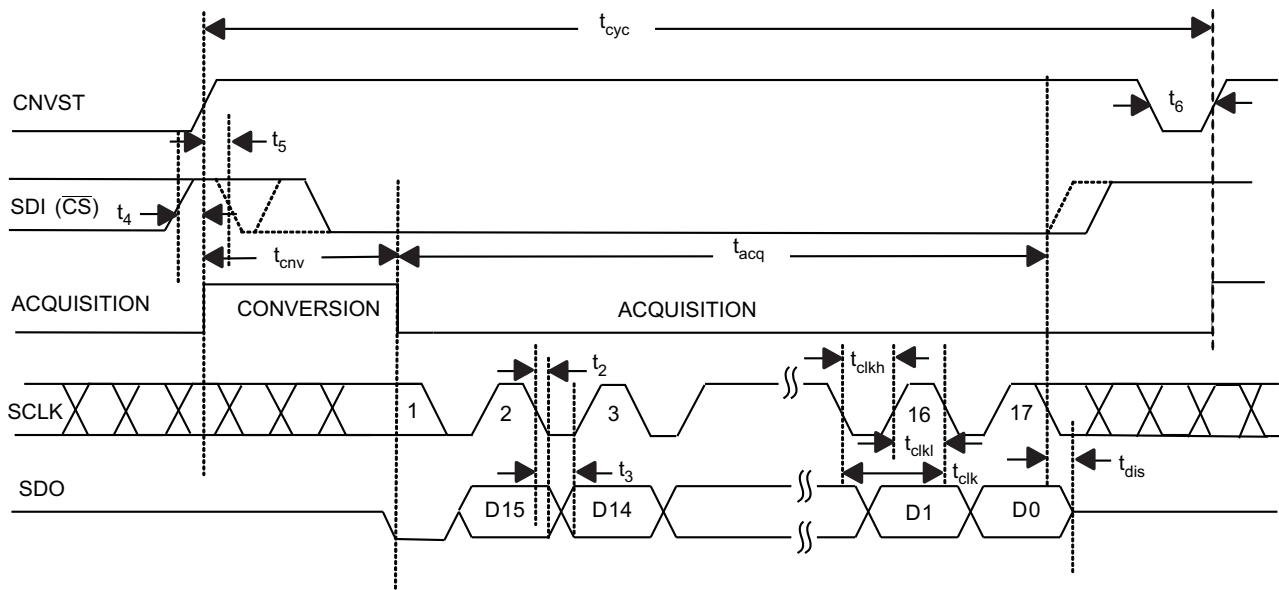


Figure 55. Interface Timing Diagram, 4-Wire \overline{CS} Mode With Busy Indicator

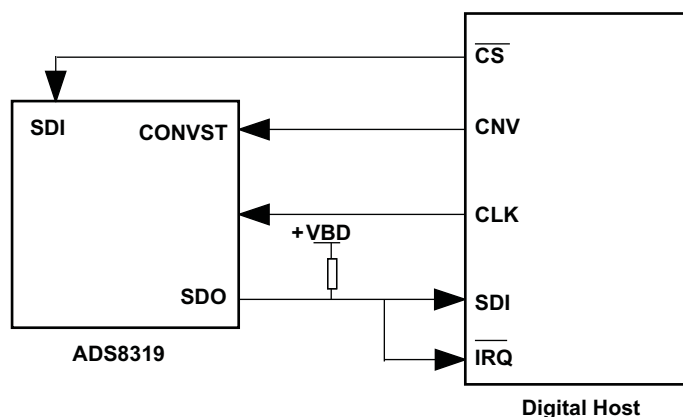


Figure 56. Connection Diagram, 4-Wire \overline{CS} Mode With Busy Indicator

When the conversion is over, the device enters the acquisition phase and powers down, forces SDO out of three state, and outputs a busy indicator bit (low level). The device outputs the MSB of the data on the first falling edge of SCLK after the conversion is over and continues to output the next lower data bits on every falling edge of SCLK. SDO goes to three state after the 17th falling edge of SCLK or SDI (\overline{CS}) high, whichever occurs first.

Care needs to be taken so that CONVST and SDI are not low together at any time during the cycle.

8.3.2 Daisy-Chain Mode

Daisy chain mode is selected if SDI is low at the time of CONVST rising edge. This mode is useful to reduce wiring and hardware like digital isolators in the applications where multiple (ADC) devices are used. In this mode all of the devices are connected in a chain (SDO of one device connected to the SDI of the next device) and data transfer is analogous to a shift register.

Like \overline{CS} mode even this mode offers operation with or without a busy indicator. The following section discusses these interface options in detail.

Device Functional Modes (continued)

8.3.2.1 Daisy-Chain Mode Without Busy Indicator

Figure 57 shows the connection diagram. SDI for device 1 is tied to ground and SDO of device 1 goes to SDI of device 2 and so on. SDO of the last device in the chain goes to the digital host. CONVST for all of the devices in the chain are tied together. In this mode there is no CS signal. The device SDO is driven low when SDI low selects daisy chain mode and the device samples the analog input and enters the conversion phase. It is necessary that SCLK is low at the rising edge of CONVST so that the device does not generate a busy indicator at the end of the conversion. In this mode CONVST continues to be high from the start of the conversion until all of the data bits are read. Once started, conversion continues irrespective of the state of SCLK.

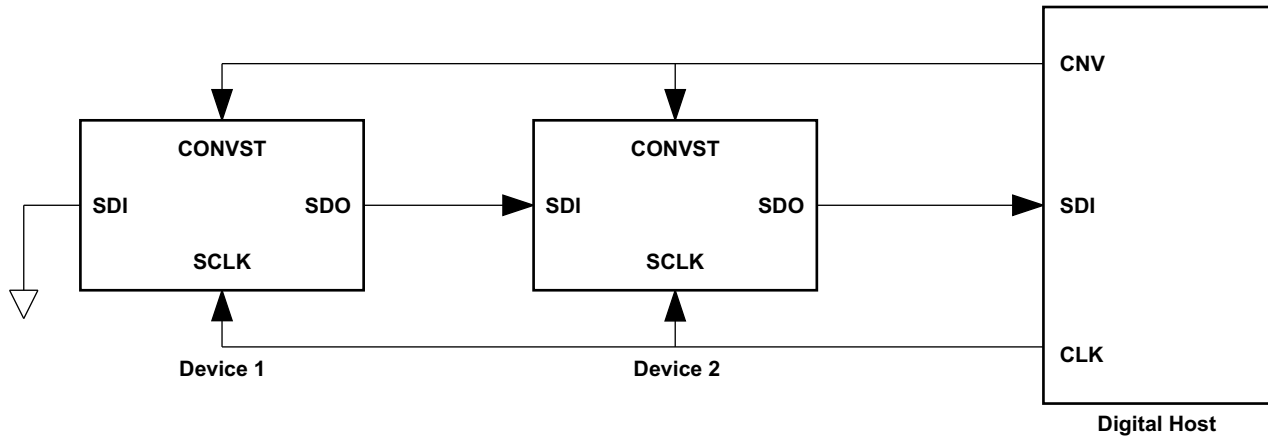


Figure 57. Connection Diagram, Daisy-Chain Mode Without Busy Indicator (SDI = 0)

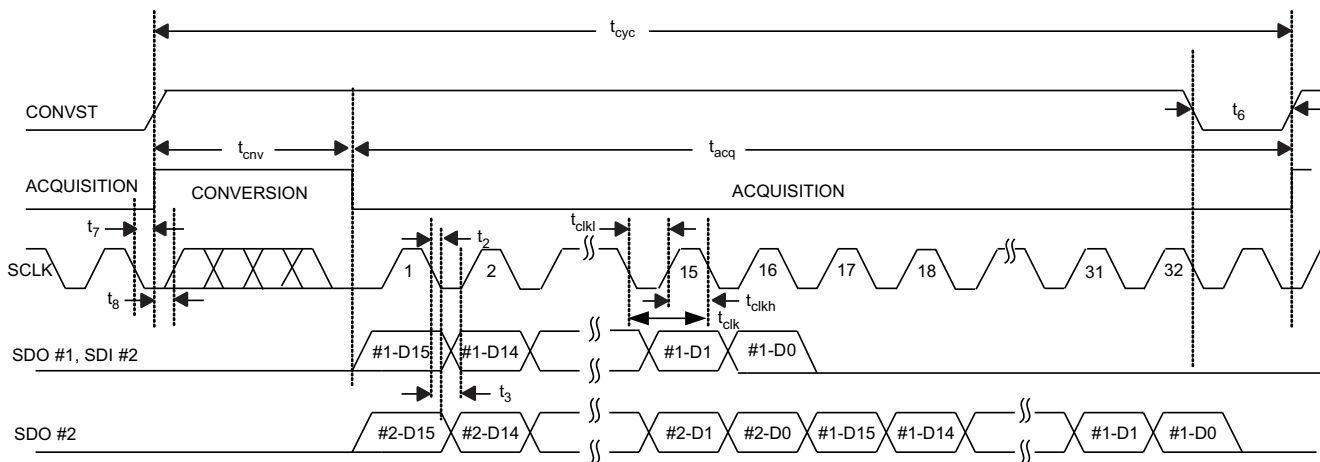


Figure 58. Interface Timing Diagram, Daisy-Chain Mode Without Busy Indicator

At the end of the conversion, every device in the chain initiates output of its conversion data starting with the MSB bit. Further the next lower data bit is output on every falling edge of SCLK. While every device outputs its data on the SDO pin, it also receives previous device data on the SDI pin (other than device #1) and stores it in the shift register. The device latches incoming data on every falling edge of SCLK. SDO of the first device in the chain goes low after the 16th falling edge of SCLK. All subsequent devices in the chain output the stored data from the previous device in MSB first format immediately following their own data word.

It needs $16 \times N$ clocks to read data for N devices in the chain.

Device Functional Modes (continued)

8.3.2.2 Daisy-Chain Mode With Busy Indicator

Figure 59 shows the connection diagram. SDI for device 1 is wired to its CONVST and CONVST for all the devices in the chain are wired together. SDO of device 1 goes to SDI of device 2 and so on. SDO of the last device in the chain goes to the digital host. In this mode there is no CS signal. On the rising edge of CONVST, all of the device in the chain sample the analog input and enter the conversion phase. For the first device, SDI and CONVST are wired together, and the setup time of SDI to rising edge of CONVST is adjusted so that the device still enters chain mode even though SDI and CONVST rise together. It is necessary that SCLK is high at the rising edge of CONVST so that the device generates a busy indicator at the end of the conversion. In this mode, CONVST continues to be high from the start of the conversion until all of the data bits are read. Once started, conversion continues irrespective of the state of SCLK.

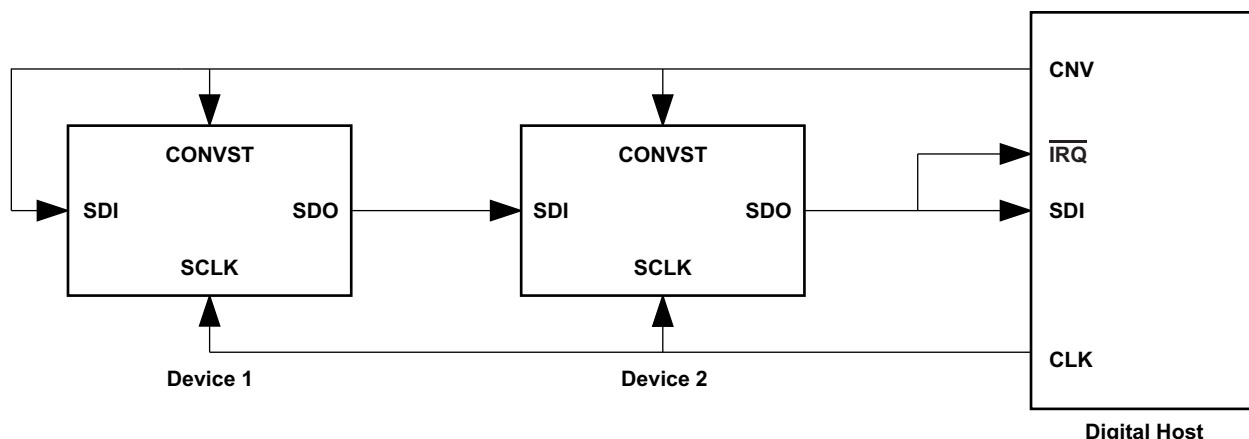


Figure 59. Connection Diagram, Daisy-Mode With Busy Indicator (SDI = 0)

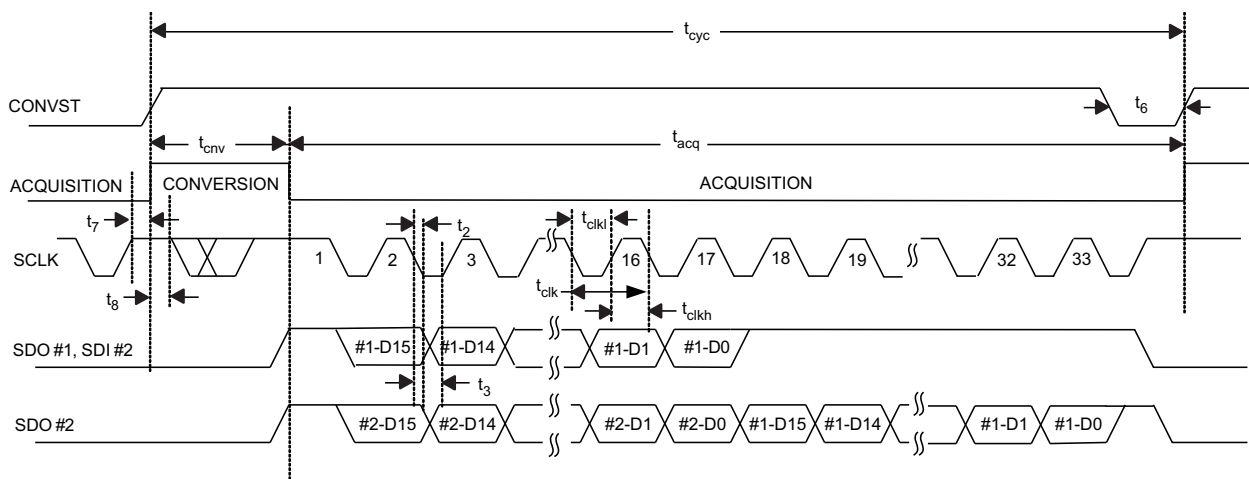


Figure 60. Interface Timing Diagram, Daisy-Chain Mode With Busy Indicator

At the end of the conversion, all the devices in the chain generate busy indicators. On the first falling edge of SCLK following the busy indicator bit, all of the devices in the chain output their conversion data starting with the MSB bit. After this the next lower data bit is output on every falling edge of SCLK. While every device outputs its data on the SDO pin, it also receives the previous device data on the SDI pin (except for device #1) and stores it in the shift register. Each device latches incoming data on every falling edge of SCLK. SDO of the first device in the chain goes high after the 17th falling edge of SCLK. All subsequent devices in the chain output the stored data from the previous device in MSB first format immediately following their own data word. It needs $16 \times N + 1$ clock pulses to read data for N devices in the chain.

9 Device and Documentation Support

9.1 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

9.2 Trademarks

E2E is a trademark of Texas Instruments.

SPI is a trademark of Motorola.

All other trademarks are the property of their respective owners.

9.3 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

9.4 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical packaging and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
ADS8319IBDGSR	ACTIVE	VSSOP	DGS	10	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	CEN	Samples
ADS8319IBDGST	ACTIVE	VSSOP	DGS	10	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	CEN	Samples
ADS8319IBDRCR	ACTIVE	VSON	DRC	10	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	CEP	Samples
ADS8319IBDRCT	ACTIVE	VSON	DRC	10	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	CEP	Samples
ADS8319IDGSR	ACTIVE	VSSOP	DGS	10	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	CEN	Samples
ADS8319IDGST	ACTIVE	VSSOP	DGS	10	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	CEN	Samples
ADS8319IDRCT	ACTIVE	VSON	DRC	10	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	CEP	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

⁽⁵⁾ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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TAPE AND REEL INFORMATION



QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS8319IBDGSR	VSSOP	DGS	10	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
ADS8319IBDGST	VSSOP	DGS	10	250	180.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
ADS8319IBDRCR	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
ADS8319IBDRCT	VSON	DRC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
ADS8319IDGSR	VSSOP	DGS	10	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
ADS8319IDGST	VSSOP	DGS	10	250	180.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
ADS8319IDRCT	VSON	DRC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2

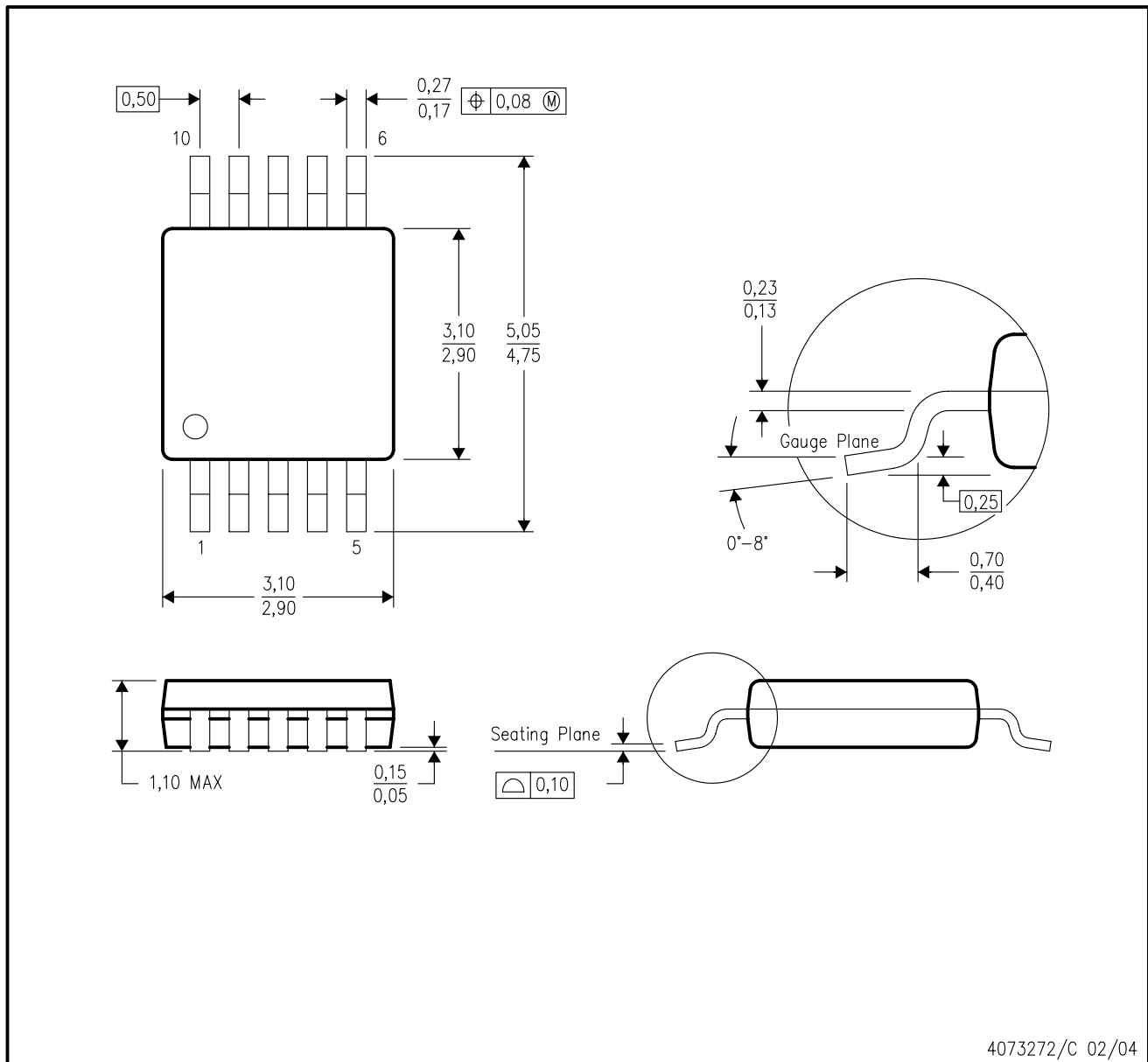
TAPE AND REEL BOX DIMENSIONS


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADS8319IBDGSR	VSSOP	DGS	10	2500	367.0	367.0	35.0
ADS8319IBDGST	VSSOP	DGS	10	250	210.0	185.0	35.0
ADS8319IBDRCR	VSON	DRC	10	3000	338.1	338.1	20.6
ADS8319IBDRCT	VSON	DRC	10	250	210.0	185.0	35.0
ADS8319IDGSR	VSSOP	DGS	10	2500	367.0	367.0	35.0
ADS8319IDGST	VSSOP	DGS	10	250	210.0	185.0	35.0
ADS8319IDRCT	VSON	DRC	10	250	210.0	185.0	35.0

DGS (S-PDSO-G10)

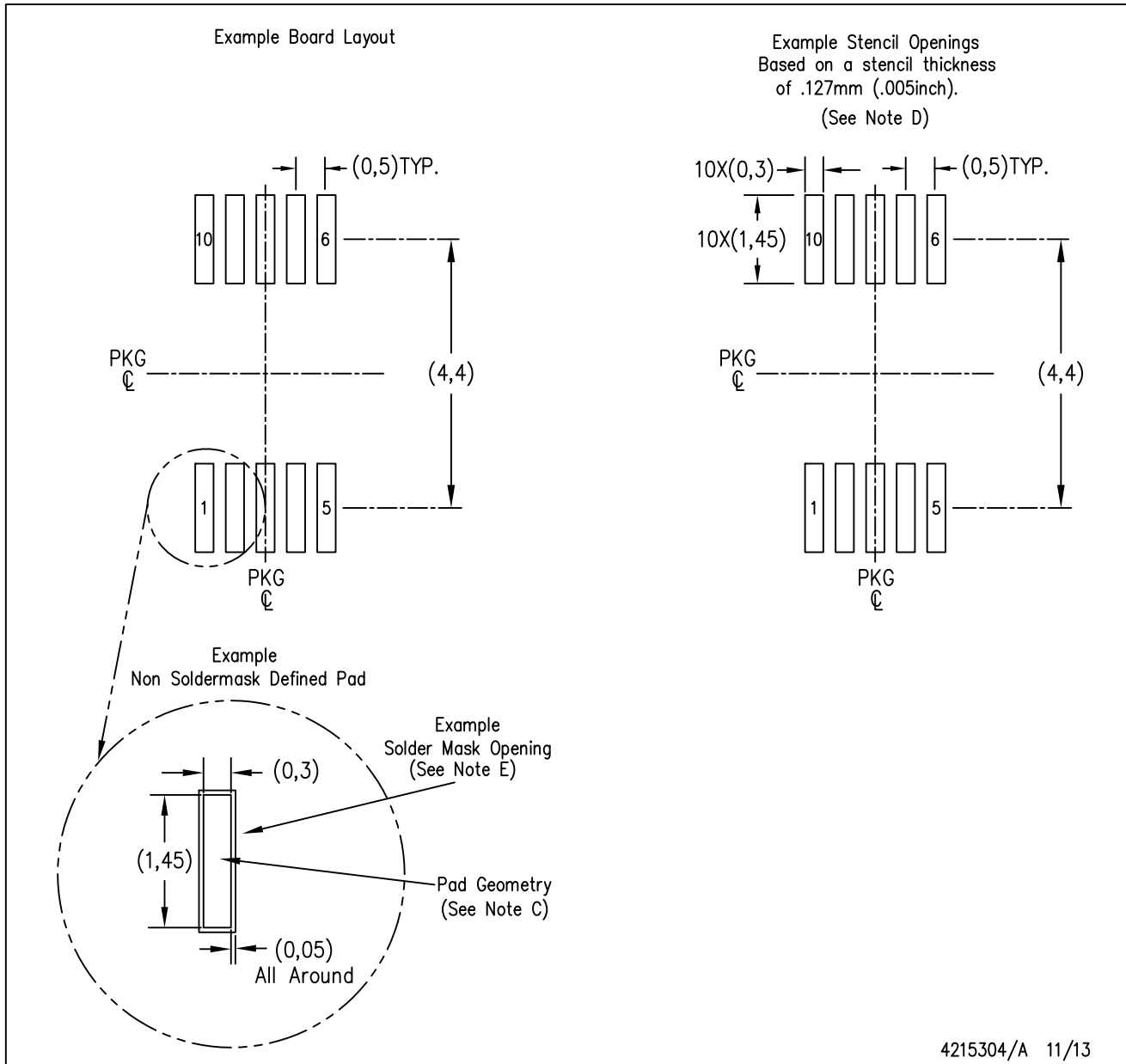
PLASTIC SMALL-OUTLINE PACKAGE



- NOTES:
- A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Body dimensions do not include mold flash or protrusion.
 - D. Falls within JEDEC MO-187 variation BA.

DGS (S-PDSO-G10)

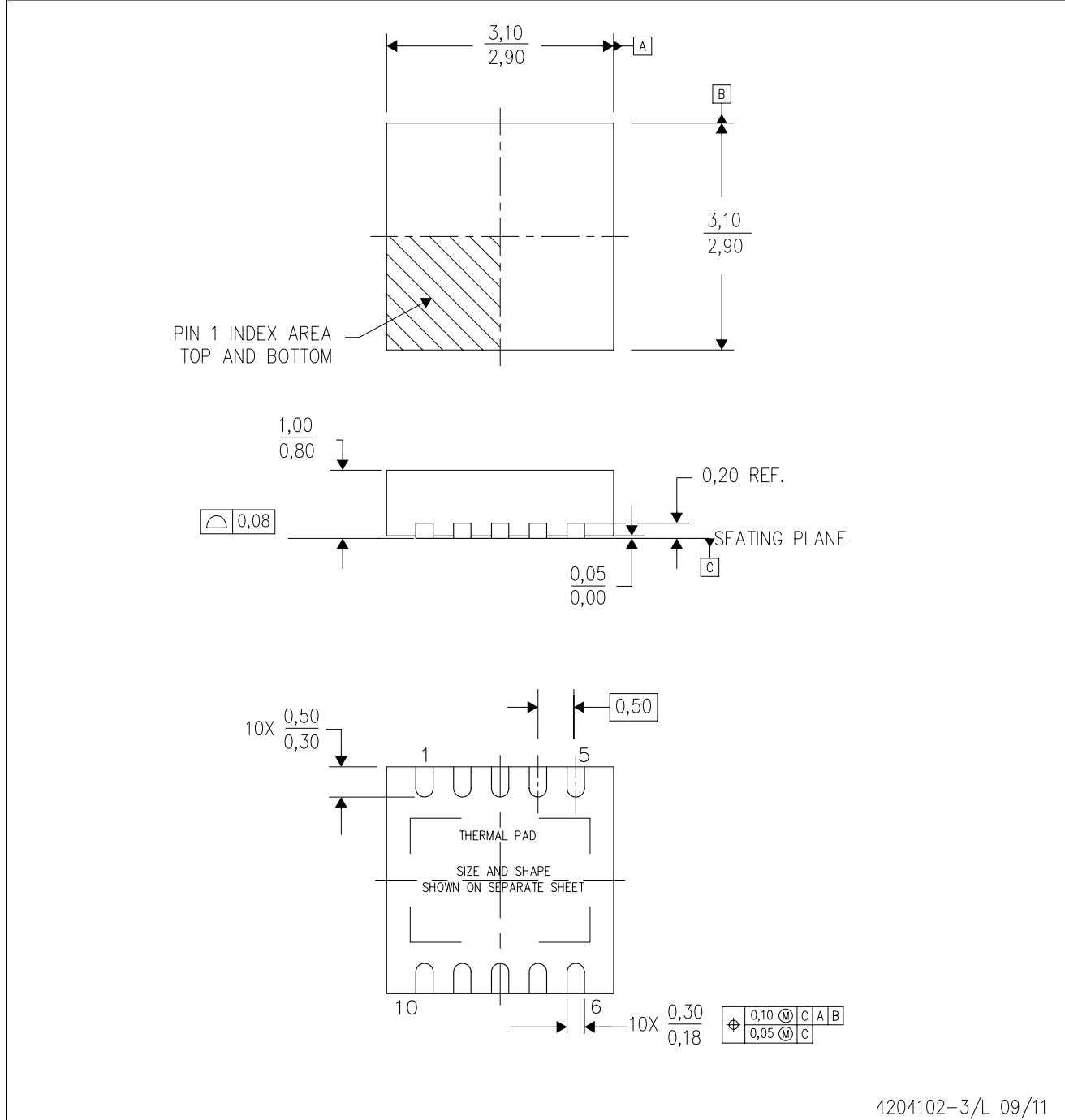
PLASTIC SMALL OUTLINE PACKAGE



- NOTES:
- All linear dimensions are in millimeters.
 - This drawing is subject to change without notice.
 - Publication IPC-7351 is recommended for alternate designs.
 - Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
 - Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

DRC (S-PVSON-N10)

PLASTIC SMALL OUTLINE NO-LEAD



4204102-3/L 09/11

- NOTES:
- All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
 - This drawing is subject to change without notice.
 - Small Outline No-Lead (SON) package configuration.
 - The package thermal pad must be soldered to the board for thermal and mechanical performance, if present.
 - See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions, if present

THERMAL PAD MECHANICAL DATA

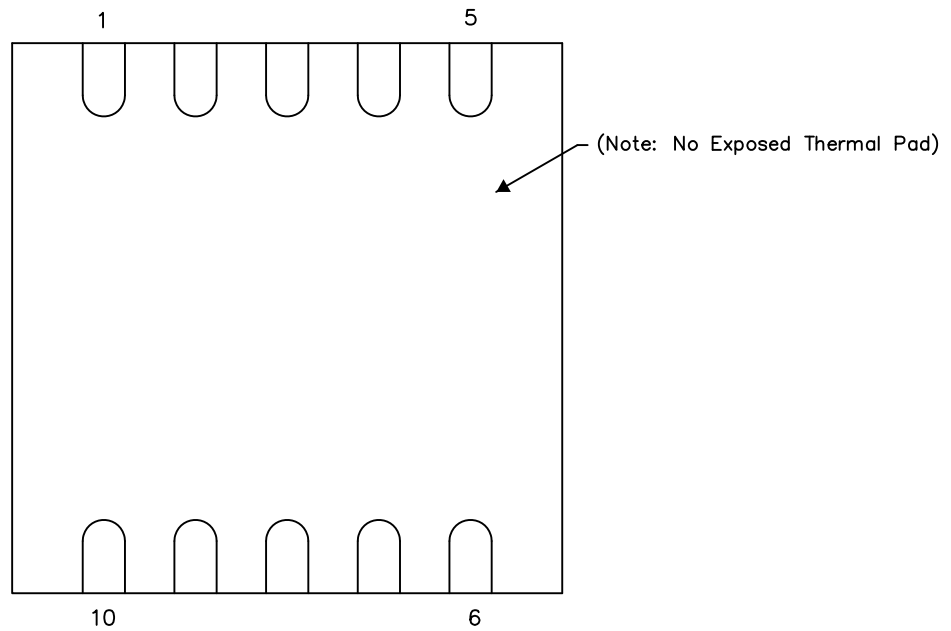
DRC (S-PVSON-N10)

PLASTIC SMALL OUTLINE NO-LEAD

THERMAL INFORMATION

This version of the package has no exposed thermal pad. This must be accounted for when estimating thermal performance.

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

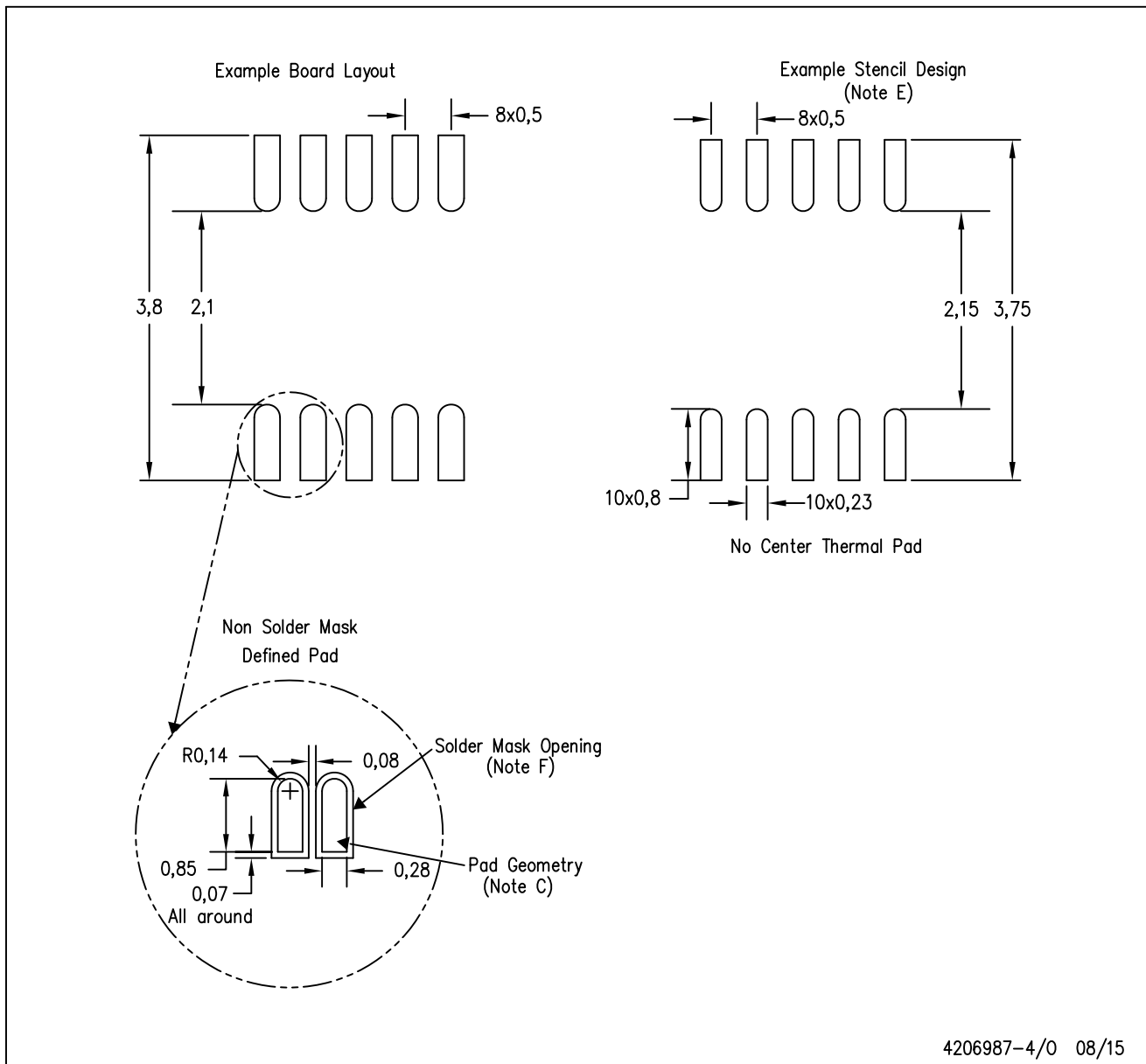


Bottom View

4206565-5/Y 08/15

DRC (S-PVSON-N10)

PLASTIC SMALL OUTLINE NO-LEAD



- NOTES:
- A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Publication IPC-7351 is recommended for alternate designs.
 - D. This package does not have a center thermal pad. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <<http://www.ti.com>>.
 - E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
 - F. Customers should contact their board fabrication site for minimum solder mask web tolerances between signal pads.

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