

TPS6116xA White LED Driver with PWM Brightness Control in 2-mm x 2-mm WSON Package

1 Features

- Input Voltage Range: 2.7 V to 18 V
- 26-V Open LED Protection for TPS61160A
38-V Open LED Protection for TPS61161A
- 200mV Reference Voltage With $\pm 2\%$ Accuracy
- PWM Interface for Brightness Control
- Built-in Soft Start
- Up to 90% Efficiency
- 2-mm x 2-mm x 0.8-mm 6-Pin WSON Package With Thermal Pad

2 Applications

- Cellular Phones
- Portable Media Players
- Ultra Mobile Devices
- GPS Receivers
- White LED Backlighting for Media Form Factor Display

3 Description

With a 40-V rated integrated switch FET, the TPS61160A/61A is a boost converter that drives LEDs in series. The boost converter runs at 600-kHz fixed switching frequency to reduce output ripple, improve conversion efficiency, and allows for the use of small external components.

The default white LED current is set with the external sensor resistor R_{set} , and the feedback voltage is regulated to 200 mV, as shown in the typical application. During the operation, the LED current can be controlled by a pulse width modulation (PWM) signal applied to the CTRL pin through which the duty cycle determines the feedback reference voltage. In PWM dimming mode, the TPS61160A/61A does not burst the LED current; therefore, it does not generate audible noises on the output capacitor. For maximum protection, the device features integrated open LED protection that disables the TPS61160A/61A to prevent the output from exceeding the absolute maximum ratings during open LED conditions.

The TPS61160A/61A is available in a space-saving, 2-mm x 2-mm WSON package with thermal pad.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	OPEN LED PROTECTION
TPS61160A	WSON (6)	TPS61160A use 26 V (typical)
TPS61161A		TPS61161A use 38 V (typical)

(1) For all available packages, see the orderable addendum at the end of the datasheet.

Typical Application of TPS61161A

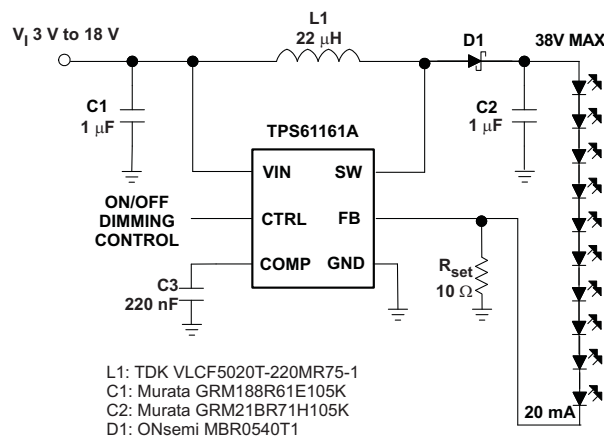


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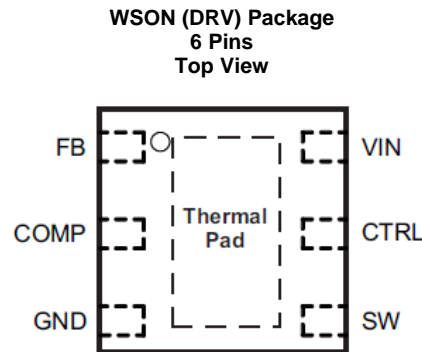
4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision A (July 2011) to Revision B	Page
• Added <i>Device Information</i> and <i>Handling Rating</i> tables, <i>Feature Description</i> , <i>Device Functional Modes</i> , <i>Application and Implementation</i> , <i>Power Supply Recommendations</i> , <i>Layout</i> , <i>Device and Documentation Support</i> , and <i>Mechanical, Packaging, and Orderable Information</i> sections; moved some curves to <i>Application Curves</i> section; change "QFN" to "SON"	1
• Changed (reversed) the $V_i=5V$ and $V_i=3.6V$ characteristic labels in Figure 3	6

Changes from Original (March 2009) to Revision A	Page
• Deleted "6 LEDs" and "10 LEDs" from the second feature bullet for TPS61160A and TPS61161A Open-LED Protection, respectively.....	1
• Deleted "for up to 10 LEDs in Series" from title	1
• Added "38V Max" to Typical Application of TPS61161A , top of LED string.....	1
• Changed from "...for driving up to 10 white LED" to "...for driving white LED" in first sentence of OPERATION section.	8
• Changed text of last sentence in "OPEN LED PROTECTION" section to clarify circuit description.....	9
• Changed Figure 11 to show separate terminals for COMP and FB.....	10
• Changed Li-Ion Driver for 6 White LEDs With External PWM Dimming Network to clarify schematic	14

5 Pin Configuration and Functions



Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
COMP	2	O	Output of the transconductance error amplifier. Connect an external capacitor to this pin to compensate the regulator.
CTRL	5	I	Control pin of the boost regulator. Enable and disable IC. PWM signal can be applied to the pin for LED brightness dimming as well.
FB	1	I	Feedback pin for current. Connect the sense resistor from FB to GND.
GND	3	O	Ground
SW	4	I	This is the switching node of the IC. Connect the inductor between the VIN and SW pin. This pin is also used to sense the output voltage for open LED protection
VIN	6	I	The input supply pin for the IC. Connect VIN to a supply voltage between 2.7 V and 18 V.
Thermal Pad			The thermal pad should be soldered to the analog ground plane. If possible, use thermal via to connect to ground plane for ideal power dissipation.

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
V _I	Supply voltages on VIN ⁽²⁾	-0.3	20	V
	Voltages on CTRL ⁽²⁾	-0.3	20	V
	Voltage on FB and COMP ⁽²⁾	-0.3	3	V
	Voltage on SW ⁽²⁾	-0.3	40	V
P _D	Continuous power dissipation	See Dissipation Ratings		
T _J	Operating junction temperature	-40	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under [Recommended Operating Conditions](#) is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to network ground terminal.

6.2 Handling Ratings

		MIN	MAX	UNIT
T_{stg}	Storage temperature range	-65	150	°C
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾		V
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾		
			4000	
			1000	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

		MIN	MAX	UNIT
V_I	Input voltage, V_{IN}	2.7	18	V
V_O	Output voltage	V_{IN}	38	V
L	Inductor ⁽¹⁾	10	22	μH
f_{dim}	PWM dimming frequency ⁽²⁾	5	100	kHz
Duty	PWM duty cycle resolution	10 kHz	0.5%	
		30 kHz	1.5%	
C_{IN}	Input capacitor	1		μF
C_O	Output capacitor ⁽¹⁾	0.47	10	μF
T_A	Operating ambient temperature	-40	85	°C
T_J	Operating junction temperature	-40	125	°C

(1) These values are recommended values that have been successfully tested in several applications. Other values may be acceptable in other applications but should be fully tested by the user.

(2) The device can support the frequency range from 1 kHz to 5 kHz, based on the specification, t_{off} . The output ripple needs to be considered in the range of 1 kHz to 5 kHz.

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS61160A, TPS61161A	UNIT
		DRV	
		6 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	140	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	20	

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).

6.5 Dissipation Ratings

BOARD PACKAGE	$R_{\theta JC}$	$R_{\theta JA}$	DERATING FACTOR ABOVE $T_A = 25^\circ\text{C}$	$T_A < 25^\circ\text{C}$	$T_A = 70^\circ\text{C}$	$T_A = 85^\circ\text{C}$
Low-K ⁽¹⁾ DRV	20°C/W	140°C/W	7.1 mW/°C	715 mW	395 mW	285 mW
High-K ⁽²⁾ DRV	20°C/W	65°C/W	15.4 mW/°C	1540 mW	845 mW	615 mW

(1) The JEDEC low-K (1s) board used to derive this data was a 3 in × 3 in, two-layer board with 2-ounce copper traces on top of the board.

(2) The JEDEC high-K (2s2p) board used to derive this data was a 3 in × 3 in, multilayer board with 1-ounce internal power and ground planes and 2-ounce copper traces on top and bottom of the board.

6.6 Electrical Characteristics

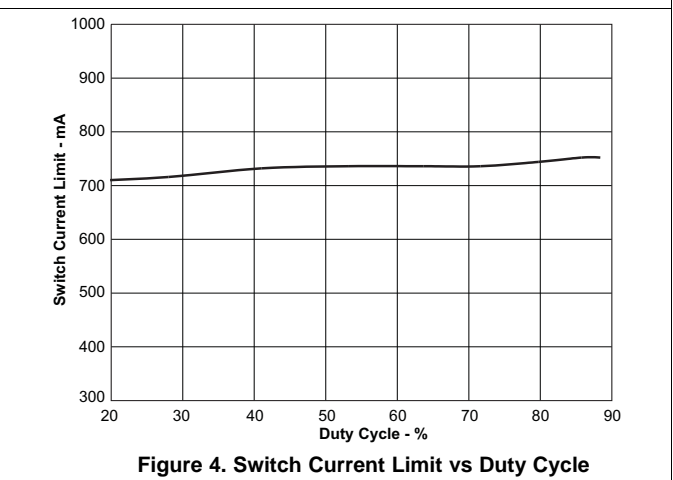
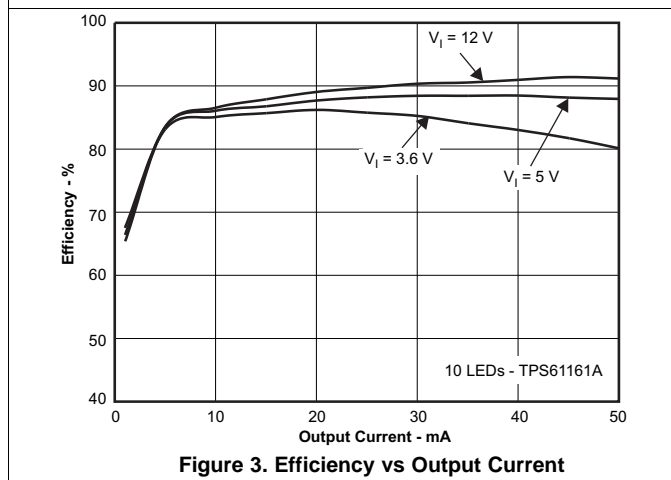
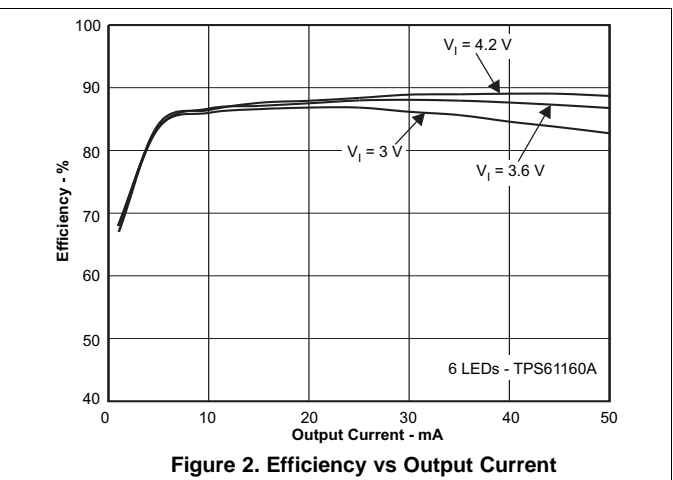
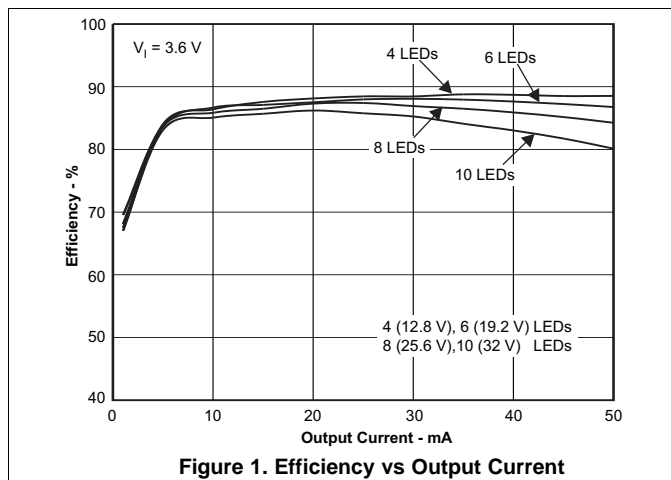
 $V_{IN} = 3.6\text{ V}$, $CTRL = V_{IN}$; for Min/Max values $T_A = -40^\circ\text{C}$ to 85°C , typical values are at $T_A = 25^\circ\text{C}$ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY CURRENT						
V_I	Input voltage range, V_{IN}		2.7		18	V
I_Q	Operating quiescent current into V_{IN}	Device PWM switching no load			1.8	mA
I_{SD}	Shutdown current	$CTRL = GND$, $V_{IN} = 4.2\text{ V}$			1	μA
UVLO	Undervoltage lockout threshold	V_{IN} falling		2.2	2.5	V
V_{hys}	Undervoltage lockout hysteresis			70		mV
ENABLE AND REFERENCE CONTROL						
$V_{(CTRLh)}$	CTRL logic high voltage	$V_{IN} = 2.7\text{ V}$ to 18 V	1.2			V
$V_{(CTRLl)}$	CTRL logic low voltage	$V_{IN} = 2.7\text{ V}$ to 18 V			0.4	V
$R_{(CTRL)}$	CTRL pull down resistor		400	800	1600	k Ω
t_{off}	CTRL pulse width to shutdown	CTRL high to low	2.5			ms
VOLTAGE AND CURRENT CONTROL						
V_{REF}	Voltage feedback regulation voltage		196	200	204	mV
$V_{(REF_PWM)}$	Voltage feedback regulation voltage under brightness control	$V_{FB} = 50\text{ mV}$	47	50	53	mV
		$V_{FB} = 20\text{ mV}$	17	20	23	
I_{FB}	Voltage feedback input bias current	$V_{FB} = 200\text{ mV}$			2	μA
f_S	Oscillator frequency		500	600	700	kHz
D_{max}	Maximum duty cycle	$V_{FB} = 100\text{ mV}$	90%	93%		
t_{min_on}	Minimum on pulse width			40		ns
I_{sink}	Comp pin sink current			100		μA
I_{source}	Comp pin source current			100		μA
G_{ea}	Error amplifier transconductance		240	320	400	μmho
R_{ea}	Error amplifier output resistance			6		M Ω
f_{ea}	Error amplifier crossover frequency	5 pF connected to COMP		500		kHz
POWER SWITCH						
$R_{DS(on)}$	N-channel MOSFET on-resistance	$V_{IN} = 3.6\text{ V}$		0.3	0.6	Ω
		$V_{IN} = 3\text{ V}$			0.7	
I_{LN_NFET}	N-channel leakage current	$V_{SW} = 35\text{ V}$, $T_A = 25^\circ\text{C}$			1	μA
OC and OLP						
I_{LIM}	N-Channel MOSFET current limit	$D = D_{max}$	0.56	0.7	0.84	A
I_{LIM_Start}	Start up current limit	$D = D_{max}$		0.4		A
t_{Half_LIM}	Time step for half current limit			5		ms
V_{ovp}	Open LED protection threshold	Measured on the SW pin, TPS61160A TPS61161A	25	26	27	V
			37	38	39	
$V_{(FB_OVP)}$	Open LED protection threshold on FB	Measured on the FB pin, percentage of V_{ref} , $V_{ref} = 200\text{ mV}$ and 20 mV		50%		
t_{REF}	V_{REF} filter time constant			180		μs
t_{step}	V_{REF} ramp up time			213		μs
THERMAL SHUTDOWN						
$T_{shutdown}$	Thermal shutdown threshold			160		$^\circ\text{C}$
$T_{hysteresis}$	Thermal shutdown threshold hysteresis			15		$^\circ\text{C}$

6.7 Typical Characteristics

Table 1. Table of Graphs

		FIGURE
Efficiency TPS61160A/61A	$V_{IN} = 3.6\text{ V}$; 4, 6, 8, 10 LEDs; $L = 22\ \mu\text{H}$	Figure 1
Efficiency TPS61160A		Figure 2
Efficiency TPS61161A		Figure 3
Current limit	$T_A = 25^\circ\text{C}$	Figure 4
Current limit		Figure 5
PWM dimming linearity	$V_{IN} = 3.6\text{ V}$; PWM Freq = 10 kHz and 40 kHz	Figure 6
Output ripple at PWM dimming	8 LEDs; $V_{IN} = 3.6\text{ V}$; $I_{LOAD} = 20\text{ mA}$; PWM Freq = 10 kHz	Figure 7
Switching waveform	8 LEDs; $V_{IN} = 3.6\text{ V}$; $I_{LOAD} = 20\text{ mA}$; $L = 22\ \mu\text{H}$	Figure 8
Start-up	8 LEDs; $V_{IN} = 3.6\text{ V}$; $I_{LOAD} = 20\text{ mA}$; $L = 22\ \mu\text{H}$	Figure 9
Open LED protection	8 LEDs; $V_{IN} = 3.6\text{ V}$; $I_{LOAD} = 20\text{ mA}$; $L = 22\ \mu\text{H}$	Figure 10



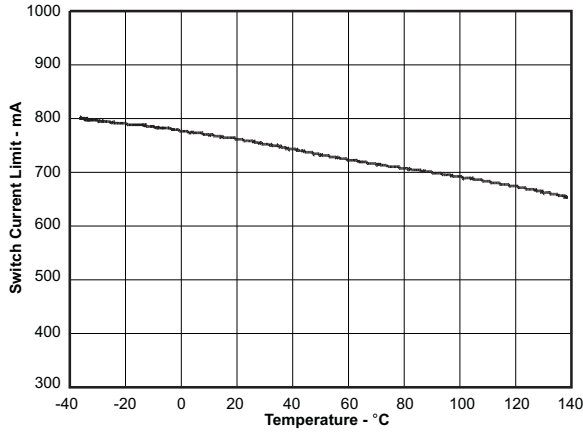


Figure 5. Switch Current Limit vs Temperature

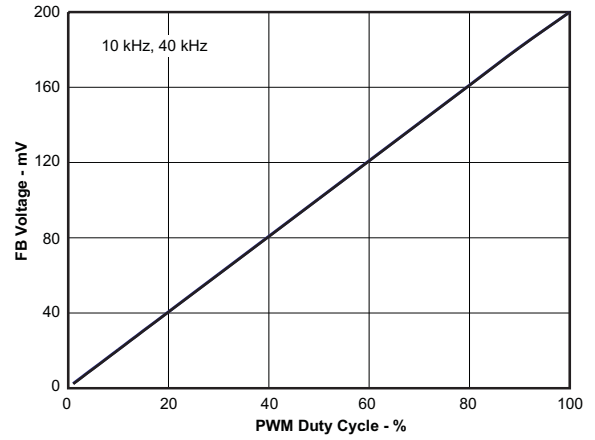


Figure 6. FB Voltage vs PWM Duty Cycle

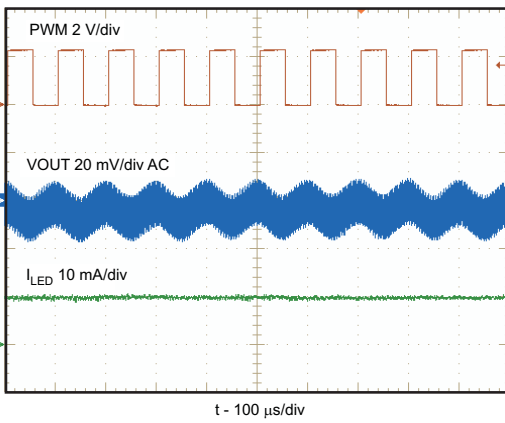


Figure 7. Output Ripple at PWM Dimming

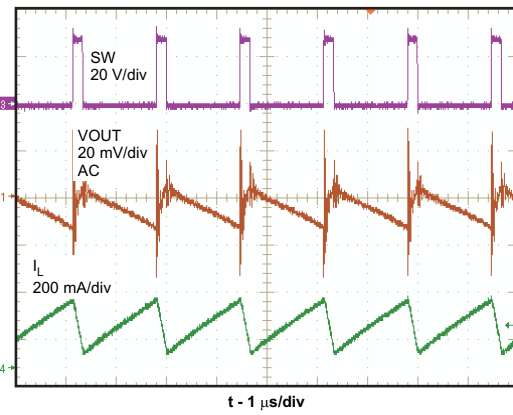


Figure 8. Switching Waveform

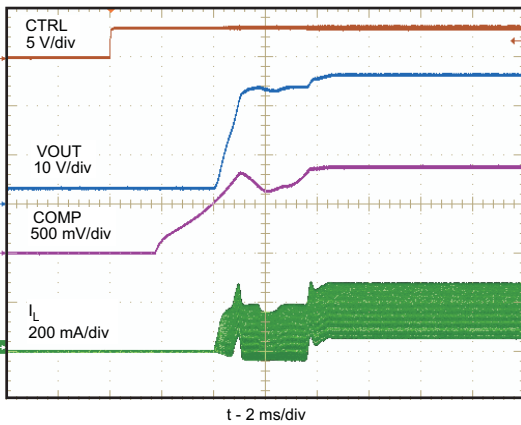


Figure 9. Start-Up

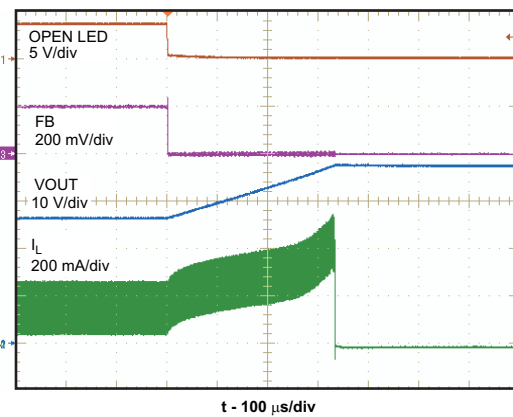


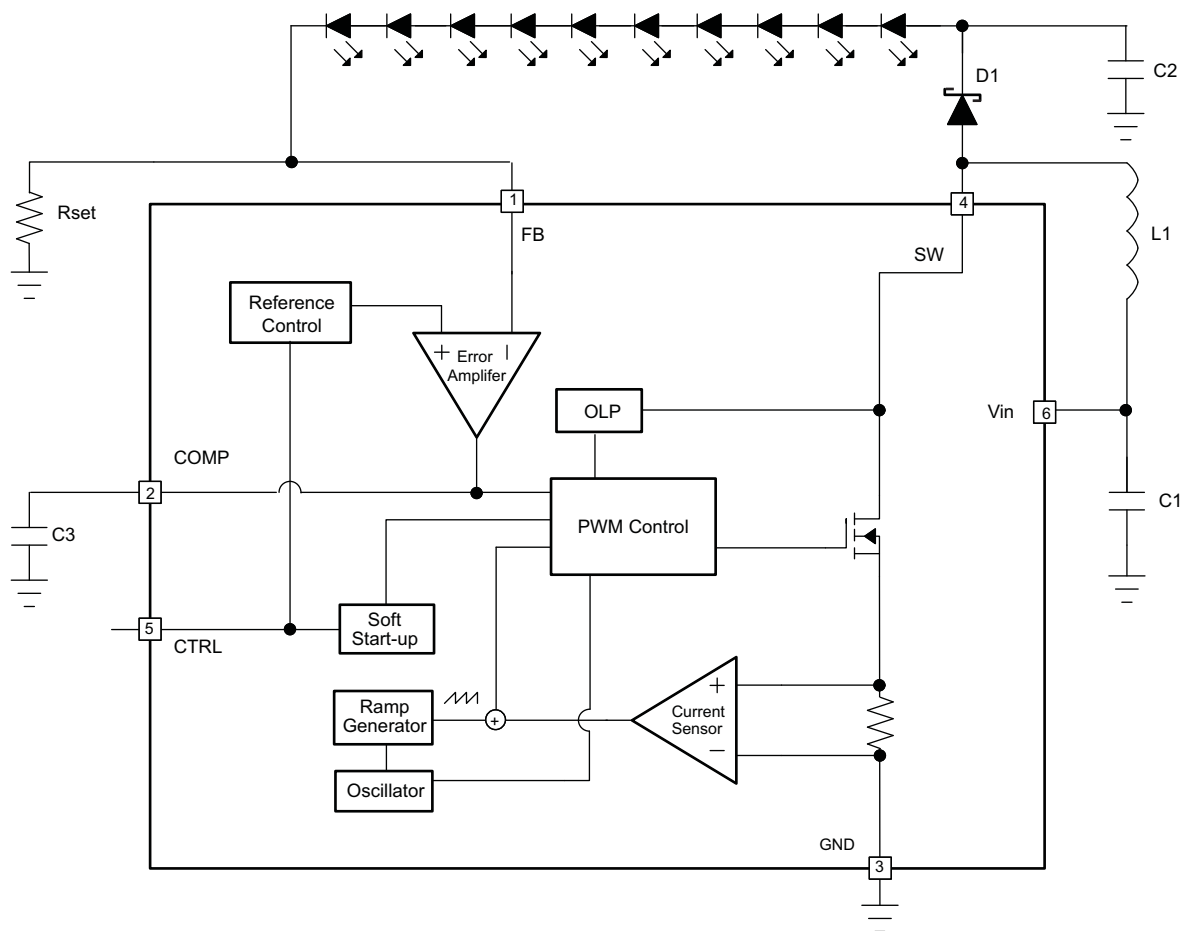
Figure 10. Open LED Protection

7 Detailed Description

7.1 Overview

The TPS61160A/61A is a high-efficiency, high output voltage boost converter in small package size that is ideal for driving white LED in series. The serial LED connection provides even illumination by sourcing the same output current through all LEDs, eliminating the need for expensive factory calibration. The device integrates 40-V/0.7-A switch FET and operates in pulse width modulation (PWM) with 600-kHz fixed switching frequency. For operation see the block diagram. The duty cycle of the converter is set by the error amplifier output and the current signal applied to the PWM control comparator. The control architecture is based on traditional current-mode control; therefore, a slope compensation is added to the current signal to allow stable operation for duty cycles larger than 50%. The feedback loop regulates the FB pin to a low reference voltage (200 mV typical), reducing the power dissipation in the current sense resistor.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Soft Start-Up

Soft-start circuitry is integrated into the IC to avoid a high inrush current during start-up. After the device is enabled, the voltage at FB pin ramps up to the reference voltage in 32 steps, each step takes 213 μ s. This ensures that the output voltage rises slowly to reduce the input current. Additionally, for the first 5 msec after the COMP voltage ramps, the current limit of the switch is set to half of the normal current limit spec. During this period, the input current is kept below 400 mA (typical). See the start-up waveform of a typical example, [Figure 9](#).

Feature Description (continued)

7.3.2 Open LED Protection

Open LED protection circuitry prevents IC damage as the result of white LED disconnection. The TPS61160A/61A monitors the voltage at the SW pin and FB pin during each switching cycle. The circuitry turns off the switch FET and shuts down the IC when both of the following conditions persist for 8 switching clock cycles: (1) the SW voltage exceeds the V_{OVP} threshold and (2) the FB voltage is less than half of regulation voltage. As a result, the output voltage falls to the level of the input supply. The device remains in shutdown mode until it is enabled by toggling the CTRL pin logic. To allow the use of inexpensive low-voltage output capacitor, the TPS61160A/61A has different open lamp protection thresholds. The threshold is set at 26 V for the TPS61160A and 38 V for the TPS61161A. Select the appropriate device so that the product of the number of external LEDs and each LED's maximum forward voltage plus the 200 mV reference voltage does not exceed the minimum OVP threshold or $(n_{LEDs} \times V_{LED(MAX)} + 200 \text{ mV} \leq V_{OVP(MIN)})$.

7.3.3 Shutdown

The TPS61160A/61A enters shutdown mode when the CTRL voltage is logic low for more than 2.5 ms. During shutdown, the input supply current for the device is less than 1 μA (max). Although the internal FET does not switch in shutdown, there is still a DC current path between the input and the LEDs through the inductor and Schottky diode. The minimum forward voltage of the LED array must exceed the maximum input voltage to ensure that the LEDs remain off in shutdown; however, in the typical application with two or more LEDs, the forward voltage is large enough to reverse bias the Schottky and keep leakage current low.

7.3.4 Current Program

The FB voltage is regulated by a low 0.2-V reference voltage. The LED current is programmed externally using a current-sense resistor in series with the LED string. The value of the RSET is calculated using [Equation 1](#):

$$I_{LED} = \frac{V_{FB}}{R_{SET}}$$

where

- I_{LED} = output current of LEDs
- V_{FB} = regulated voltage of FB
- R_{SET} = current sense resistor

(1)

The output current tolerance depends on the FB accuracy and the current sensor resistor accuracy.

7.3.5 PWM Brightness Dimming

When the CTRL pin is constantly high, the FB voltage is regulated to 200 mV typically. However, the CTRL pin allows a PWM signal to reduce this regulation voltage; therefore, it achieves LED brightness dimming. The relationship between the duty cycle and FB voltage is given by [Equation 2](#).

$$V_{FB} = \text{Duty} \times 200 \text{ mV}$$

where

- Duty = duty cycle of the PWM signal
- 200 mV = internal reference voltage

(2)

As shown in [Figure 11](#), the IC chops up the internal 200-mV reference voltage at the duty cycle of the PWM signal. The pulse signal is then filtered by an internal low pass filter. The output of the filter is connected to the error amplifier as the reference voltage for the FB pin regulation. Therefore, although a PWM signal is used for brightness dimming, only the WLED DC current is modulated, which is often referred as analog dimming. This eliminates the audible noise which often occurs when the LED current is pulsed in replica of the frequency and duty cycle of PWM control. Unlike other scheme which filters the PWM signal for analog dimming, TPS61160A/61A regulation voltage is independent of the PWM logic voltage level which often has large variations.

For optimum performance, use the PWM dimming frequency in the range of 5 kHz to 100 kHz. The requirement of minimum dimming frequency comes from the output ripple. Low frequency causes high output ripple. Since the CTRL pin is logic only pin, applying an external RC filter to the pin does not work.

Feature Description (continued)

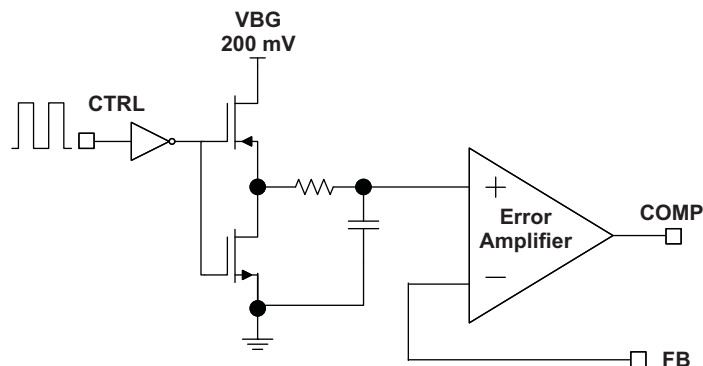


Figure 11. Block Diagram of Programmable FB Voltage Using PWM Signal

To use lower PWM dimming, add an external RC network connected to the FB pin as shown in [Figure 15](#)).

7.3.6 Undervoltage Lockout

An undervoltage lockout prevents operation of the device at input voltages below typical 2.2 V. When the input voltage is below the undervoltage threshold, the device is shutdown and the internal switch FET is turned off. If the input voltage rises by undervoltage lockout hysteresis, the IC restarts.

7.3.7 Thermal Shutdown

An internal thermal shutdown turns off the device when the typical junction temperature of 160°C is exceeded. The device is released from shutdown automatically when the junction temperature decreases by 15°C.

7.4 Device Functional Modes

7.4.1 Operation with CTRL

When the CTRL pin is held below the VIL threshold, the device is disabled, and switching is inhibited. The IC quiescent current is reduced in this state. When V_{IN} is above the UVLO threshold, and the CTRL terminal is increased above the VIH threshold the soft-start sequence initiates then the device becomes active.

7.4.2 External PWM Dimming

For assistance in selecting the proper values for Rset, R1-R3, RFLTR, CFLTR and D2 for the specific application, refer to *How to Use Analog Dimming With the TPS6116x* (SLVA471) and/or *Design Tool for Analog Dimming Using a PWM Signal* (<http://www.ti.com/lit/zip/slvc366>). Also see [Choosing Component Values](#) section below.

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The TPS61160A/61A provides a complete high-performance LED lighting solution for mobile devices supporting a single string of 6 (TPS61160A) or 10 (TPS61161A) white LEDs.

8.2 Typical Applications

8.2.1 Typical Application of TPS61161A

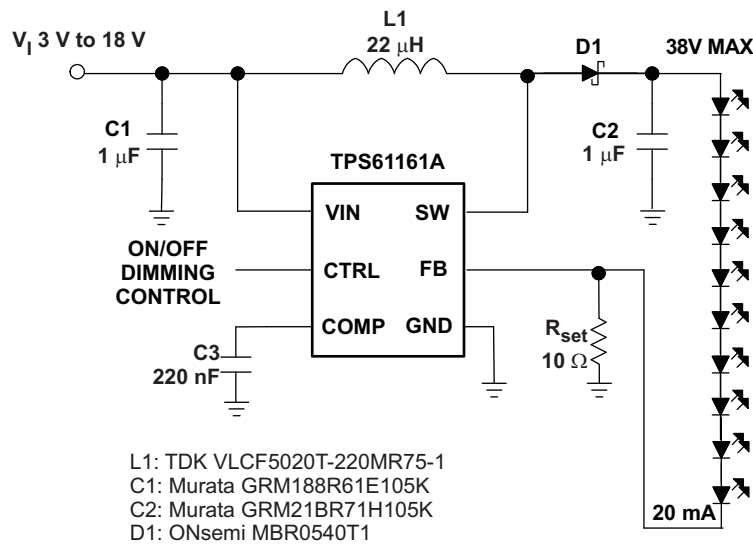


Figure 12. Typical Application of TPS61161A

8.2.1.1 Design Requirements

DESIGN PARAMETER	EXAMPLE VALUE
Inductor	22 μ H
Minimum input voltage	3 V
Number of series LED	10
LED maximum forward voltage (Vf)	3.3 V
Schottky diode forward voltage (Vf)	0.2 V
Efficiency (η)	85%
Switching frequency (SW)	600 kHz

Applying [Equation 3](#) and [Equation 4](#), when V_{IN} is 3 V, 10 LEDs output equivalent to V_{OUT} of 32.2 V, the inductor is 22 μH , the Schottky forward voltage is 0.2 V, the maximum output current is 47 mA in typical condition.

8.2.1.2 Detailed Design Procedure

8.2.1.2.1 Maximum Output Current

The overcurrent limit in a boost converter limits the maximum input current, and thus maximum input power for a given input voltage. Maximum output power is less than maximum input power due to power conversion losses. Therefore, the current limit setting, input voltage, output voltage and efficiency can all change maximum current output. The current limit clamps the peak inductor current; therefore, the ripple has to be subtracted to derive maximum DC current. The ripple current is a function of switching frequency, inductor value and duty cycle. [Equation 3](#) and [Equation 4](#) take into account of all the above factors for maximum output current calculation.

$$I_p = \frac{1}{\left[L \times F_s \times \left(\frac{1}{V_{out} + V_f - V_{in}} + \frac{1}{V_{in}} \right) \right]}$$

where

- I_p = inductor peak to peak ripple
- L = inductor value
- V_f = Schottky diode forward voltage
- F_s = switching frequency
- V_{out} = output voltage of the boost converter. It is equal to the sum of VFB and the voltage drop across LEDs

$$I_{out_max} = \frac{V_{in} \times (I_{lim} - I_p / 2) \times \eta}{V_{out}}$$

where

- I_{out_max} = maximum output current of the boost converter
- I_{lim} = over current limit
- η = efficiency

8.2.1.2.2 Inductor Selection

The selection of the inductor affects steady state operation as well as transient behavior and loop stability. These factors make it the most important component in power regulator design. There are three important inductor specifications, inductor value, DC resistance and saturation current. Considering inductor value alone is not enough.

The inductor value determines the inductor ripple current. Choose an inductor that can handle the necessary peak current without saturating, according to half of the peak-to-peak ripple current given by [Equation 3](#), pause the inductor DC current given by:

$$I_{in_DC} = \frac{V_{out} \times I_{out}}{V_{in} \times \eta}$$

Inductor values can have $\pm 20\%$ tolerance with no current bias. When the inductor current approaches saturation level, its inductance can decrease 20% to 35% from the 0A value depending on how the inductor vendor defines saturation current. Using an inductor with a smaller inductance value forces discontinuous PWM when the inductor current ramps down to zero before the end of each switching cycle. This reduces the boost converter's maximum output current, causes large input voltage ripple and reduces efficiency. Large inductance value provides much more output current and higher conversion efficiency. For these reasons, a 10 μH to 22 μH inductor value range is recommended. A 22 μH inductor optimized the efficiency for most application while maintaining low inductor peak to peak ripple. [Table 2](#) lists the recommended inductor for the TPS61160A/61A. When recommending inductor value, the factory has considered -40% and $+20\%$ tolerance from its nominal value.

TPS61160A/61A has built-in slope compensation to avoid sub-harmonic oscillation associated with current mode control. If the inductor value is lower than 10 μH , the slope compensation may not be adequate, and the loop can be unstable. Therefore, customers need to verify the inductor in their application if it is different from the recommended values.

Table 2. Recommended Inductors for TPS61160A/61A

PART NUMBER	L (μH)	DCR MAX (Ω)	SATURATION CURRENT (mA)	SIZE (L x W x H mm)	VENDOR
LQH3NPN100NM0	10	0.3	750	3 x 3 x 1.5	Murata
VLCF5020T-220MR75-1	22	0.4	750	5 x 5 x 2.0	TDK
CDH3809/SLD	10	0.3	570	4 x 4 x 1.0	Sumida
A997AS-220M	22	0.4	510	4 x 4 x 1.8	TOKO

8.2.1.2.3 Schottky Diode Selection

The high switching frequency of the TPS61160A/61A demands a high-speed rectification for optimum efficiency. Ensure that the diode average and peak current rating exceeds the average output current and peak inductor current. In addition, the diode's reverse breakdown voltage must exceed the open LED protection voltage. The ONSemiconductor MBR0540 and the ZETEX ZHCS400 are recommended for TPS61160A/61A.

8.2.1.2.4 Compensation Capacitor Selection

The compensation capacitor C3 (see [Functional Block Diagram](#)), connected from COMP pin to GND, is used to stabilize the feedback loop of the TPS61160A/61A. Use a 220-nF ceramic capacitor for C3.

8.2.1.2.5 Input and Output Capacitor Selection

The output capacitor is mainly selected to meet the requirements for the output ripple and loop stability. This ripple voltage is related to the capacitor's capacitance and its equivalent series resistance (ESR). Assuming a capacitor with zero ESR, the minimum capacitance needed for a given ripple can be calculated by

$$C_{out} = \frac{(V_{out} - V_{in}) \times I_{out}}{V_{out} \times F_s \times V_{ripple}}$$

where

- V_{ripple} = peak-to-peak output ripple (6)

The additional output ripple component caused by ESR is calculated using:

$$V_{ripple_ESR} = R_{ESR} \times I_{out} \tag{7}$$

Due to its low ESR, V_{ripple_ESR} can be neglected for ceramic capacitors, but must be considered if tantalum or electrolytic capacitors are used.

Care must be taken when evaluating a ceramic capacitor's derating under dc bias, aging and AC signal. For example, larger form factor capacitors (in 1206 size) have a resonant frequencies in the range of the switching frequency. So the effective capacitance is significantly lower. The DC bias can also significantly reduce capacitance. Ceramic capacitors can lose as much as 50% of its capacitance at its rated voltage. Therefore, leave the margin on the voltage rating to ensure adequate capacitance at the required output voltage.

The capacitor in the range of 1 μF to 4.7 μF is recommended for input side. The output requires a capacitor in the range of 0.47 μF to 10 μF . The output capacitor affects the loop stability of the boost regulator. If the output capacitor is below the range, the boost regulator can potentially become unstable. For example, if use the output capacitor of 0.1 μF , a 470 nF compensation capacitor has to be used for the loop stable.

The popular vendors for high value ceramic capacitors are:

TDK (<http://www.component.tdk.com/components.php>)

Murata (<http://www.murata.com/cap/index.html>)

8.2.1.3 Application Curves

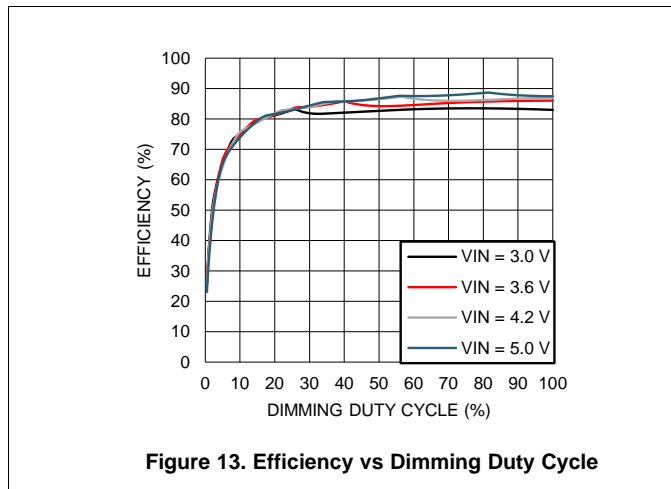


Figure 13. Efficiency vs Dimming Duty Cycle

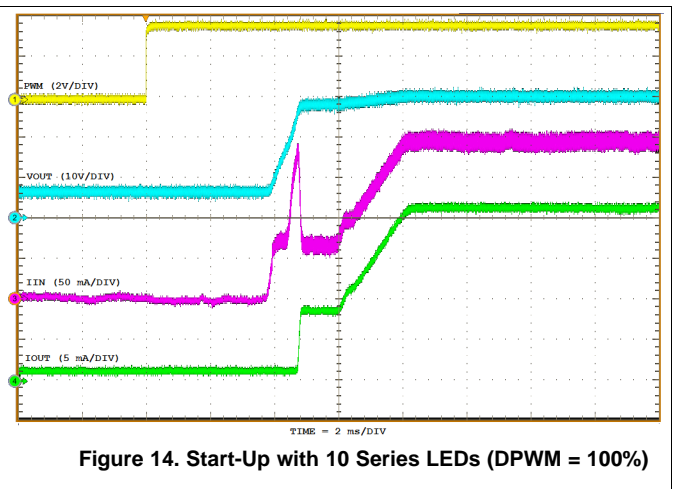


Figure 14. Start-Up with 10 Series LEDs (DPWM = 100%)

8.2.2 Li-Ion Driver for 6 White LEDs

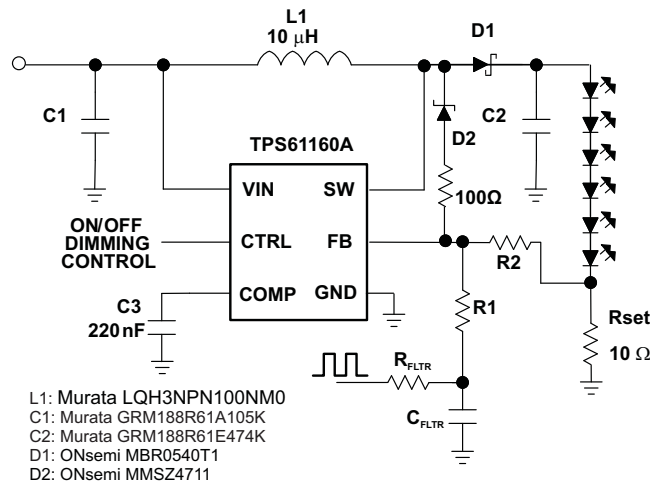


Figure 15. Li-Ion Driver for 6 White LEDs With External PWM Dimming Network

8.2.2.1 Design Requirements

DESIGN PARAMETER	EXAMPLE VALUE
Inductor	22 μ H
Minimum input voltage	3 V
Number of series LED	6
LED maximum forward voltage (Vf)	3.2 V
Schottky diode forward voltage (Vf)	0.2 V
Efficiency	82%
Switching frequency (f_{SW})	600 kHz
External PWM output voltage	3 V
External PWM frequency	20 kHz

Applying [Equation 3](#) and [Equation 4](#), when V_{IN} is 3 V, 6 LEDs output equivalent to V_{OUT} of 19.4 V, the inductor is 22 μ H, the Schottky forward voltage is 0.2 V, the maximum output current is 76 mA in typical condition.

8.2.2.2 Detailed Design Procedure

8.2.2.2.1 Choosing Component Values

As per [SLVA471](#), the values of R_{FLTR} , C_{FLTR} , R_1 , R_2 , and R_{SET} are determined by the system parameters and error tolerance. The main source of LED current error is leakage current from the FB pin. The error gets worse as the LED current decreases. The error due to leakage current is given by [Functional Block Diagram](#), where the impedance seen by the FB pin has a major impact. To reduce error due to the leakage current, the impedance seen by the FB pin needs to be small. Because R_2 is much smaller than $R_1 + R_{FLTR}$, R_2 must be chosen to be small to minimize the impedance seen by the FB pin. In general, R_2 must be chosen to be 1 k Ω or less. If greater accuracy at smaller currents is needed, then R_2 must be chosen to be even smaller.

$$\%error = \frac{I_{FB}}{\frac{V_{FB}}{(R_1 + R_{FLTR}) // R_2} - \frac{D \times V_{PWM(H)} + (1 - D)V_{PWM(L)}}{R_1 + R_{FLTR}}} \quad (8)$$

Once R_2 has been chosen, the value of R_{SET} and $R_1 + R_{FLTR}$ can be calculated using [Equation 9](#), [Equation 10](#), [Equation 11](#), and [Equation 12](#). The individual values of R_1 and R_{FLTR} can be any combination that sums up to $R_1 + R_{FLTR}$. In general, choosing R_1 and R_{FLTR} to be the same value gives a minimum requirement for C_{FLTR} .

$$V_{PWM(min)} = D_{(min)}V_{PWM(H)} + (1 - D_{(min)})V_{PWM(L)} \quad (9)$$

$$V_{PWM(max)} = D_{(max)}V_{PWM(H)} + (1 - D_{(max)})V_{PWM(L)} \quad (10)$$

$$R_{SET} = \frac{V_{FB}(V_{PWM(max)} - V_{PWM(min)})}{V_{PWM(max)}I_{LED(max)} - V_{FB}I_{LED(max)} + V_{FB}I_{LED(min)} - V_{PWM(min)}I_{LED(min)}} \quad (11)$$

$$R_1 + R_{FLTR} = \frac{R_2(I_{LED(max)}(V_{PWM(max)} - V_{FB}) - I_{LED(min)}(V_{PWM(min)} - V_{FB}))}{V_{FB}(I_{LED(max)} - I_{LED(min)})} + \frac{V_{PWM(max)} - V_{PWM(min)}}{I_{LED(max)} - I_{LED(min)}} \quad (12)$$

Finally, C_{FLTR} can be chosen based on the amount of filtering desired or to provide a gradual dimming effect that is popular in many lighting products. At a minimum, C_{FLTR} must be chosen to provide at least 20 dB of attenuation at the PWM frequency. [Equation 13](#) can be used to calculate the minimum capacitor value to provide this attenuation.

$$C_{FLTR} = \frac{1}{2\pi (R_{FLTR} // R_1) \frac{f_{pwm}}{10}} \quad (13)$$

To provide gradual dimming, a large capacitor must be chosen to provide a long transient time when changing the PWM duty cycle. [Equation 14](#) shows how to calculate the recommended corner frequency of the RC filter based on the 10% to 90% rise time. Once the corner frequency is known, it can be used to calculate the required capacitor using [Equation 15](#).

$$f_{RC} = \frac{0.35}{t_r} \quad (14)$$

$$C_{FLTR} = \frac{1}{2\pi (R_{FLTR} // R_1) f_{RC}} \quad (15)$$

For example, a design with R_{FLTR} and R_1 equal to 10 k Ω and a desired rise time of 500 ms requires a corner frequency of 0.7 Hz and a capacitor of 47 μ F.

8.2.2.3 Application Curves

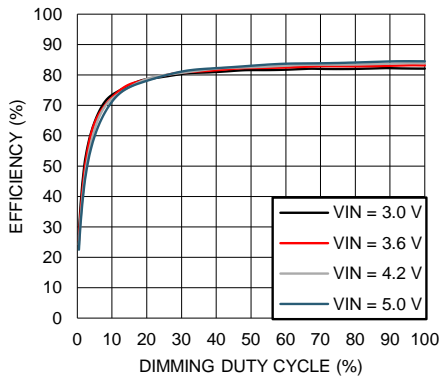


Figure 16. Efficiency vs Dimming Duty Cycle

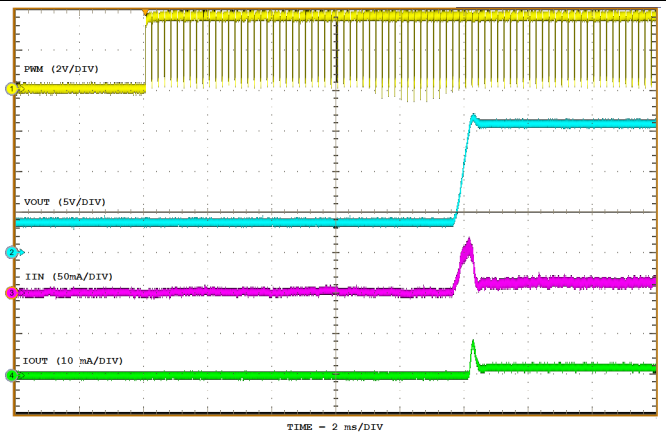


Figure 17. Start-Up with 6 series LEDs (External PWM, DPWM = 10%)

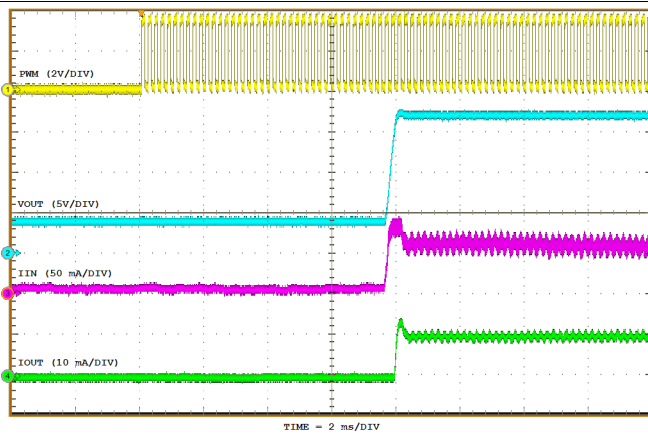


Figure 18. Start-Up with 6 Series LEDs (External PWM, DPWM = 50%)

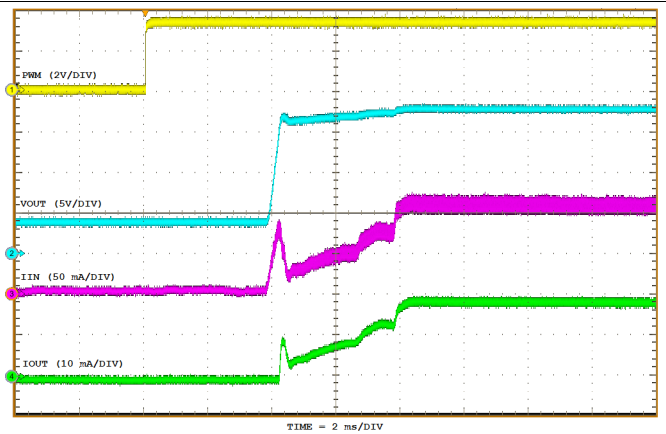
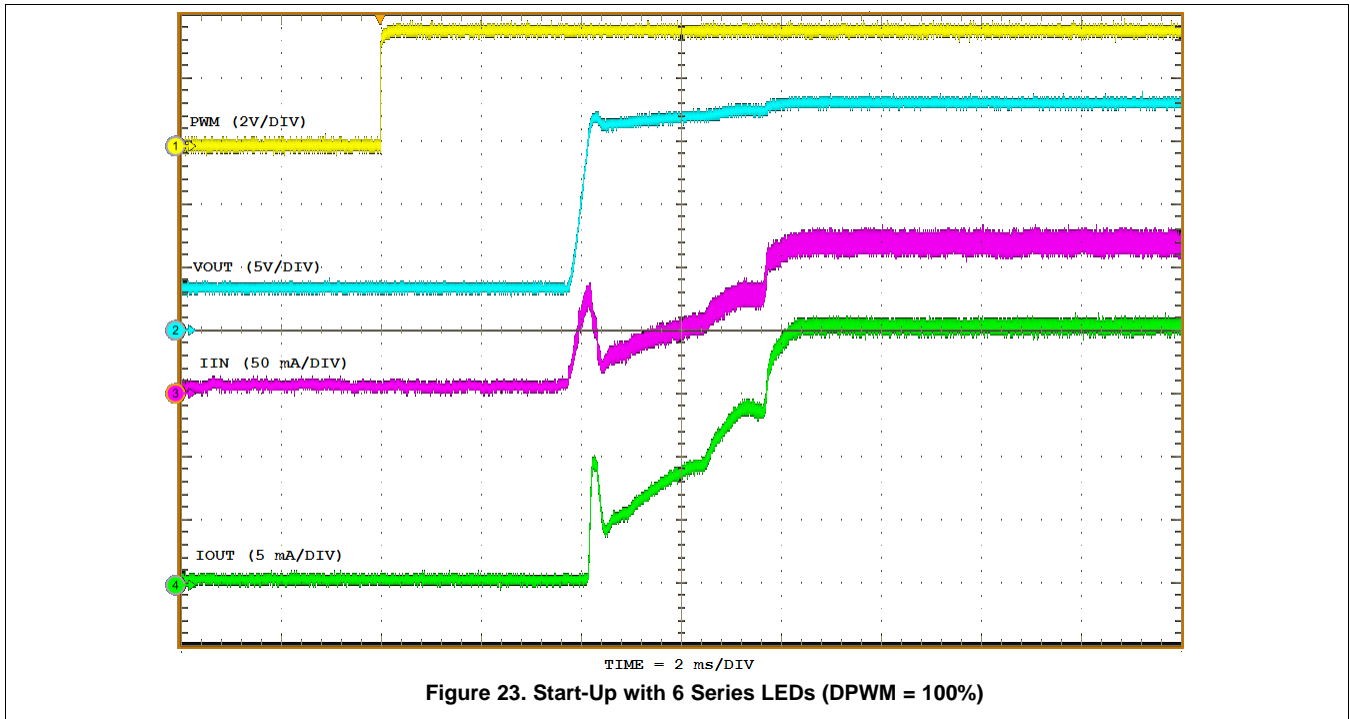


Figure 19. Start-Up with 6 Series LEDs (External PWM, DPWM = 100%)



8.2.4 Li-Ion Driver for 8 White LEDs

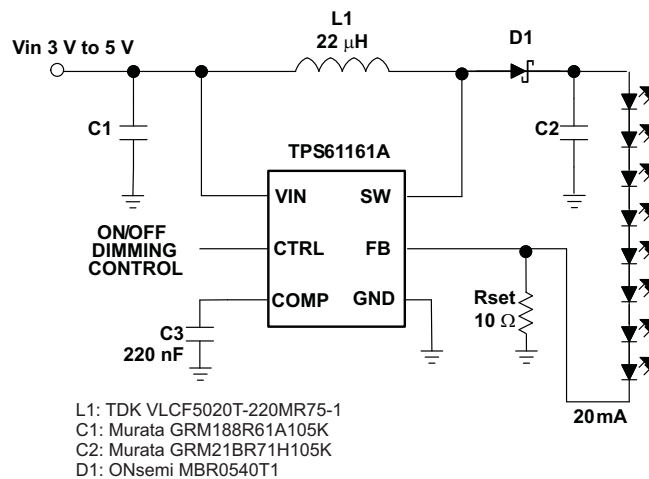


Figure 24. Li-Ion Driver for 8 White LEDs

8.2.4.1 Design Requirements

DESIGN PARAMETER	EXAMPLE VALUE
LED current	0.02 A
Minimum input voltage	3 V
Number of series LED	8
LED maximum forward voltage (Vf)	3.3 V
Schottky diode forward voltage	0.2 V
Efficiency (η)	86%
Switching frequency	600 kHz

Applying Equation 3 and Equation 4, when V_{IN} is 3 V, 8 LEDs output equivalent to V_{OUT} of 25.8 V, the inductor is 22 μ H, the Schottky forward voltage is 0.2 V, the maximum output current is 60 mA in typical condition.

8.2.4.2 Detailed Design Procedure

See [Detailed Design Procedure](#).

8.2.4.3 Application Curves

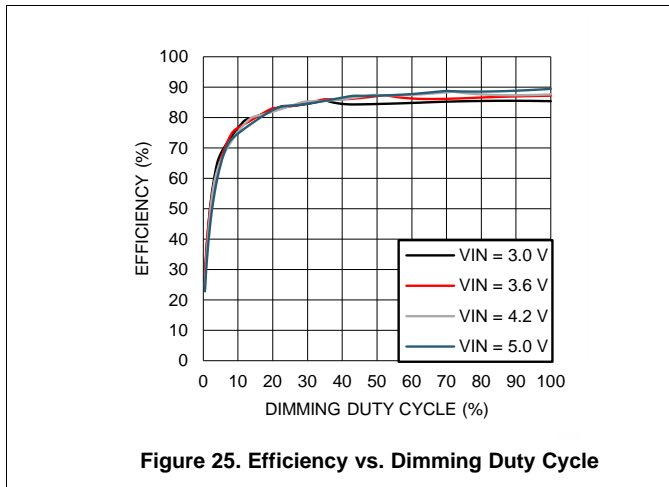


Figure 25. Efficiency vs. Dimming Duty Cycle

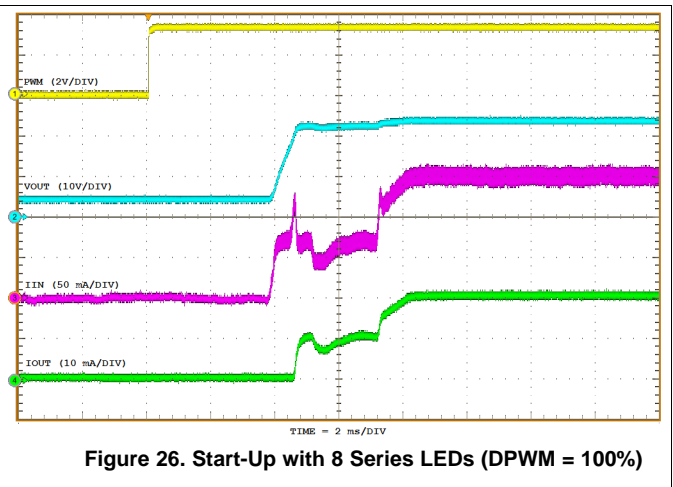


Figure 26. Start-Up with 8 Series LEDs (DPWM = 100%)

9 Power Supply Recommendations

The TPS61160A/61A is designed to operate from an input supply range of 2.7 V to 18 V. This input supply should be well regulated and provide the peak current required by the number of series LEDs and inductor selected.

10 Layout

10.1 Layout Guidelines

As for all switching power supplies, especially those high frequency and high current ones, layout is an important design step. If layout is not carefully done, the regulator could suffer from instability as well as noise problems. To reduce switching losses, the SW pin rise and fall times are made as short as possible. To prevent radiation of high frequency resonance problems, proper layout of the high frequency switching path is essential. Minimize the length and area of all traces connected to the SW pin and always use a ground plane under the switching regulator to minimize inter-plane coupling. The loop including the PWM switch, Schottky diode, and output capacitor, contains high current rising and falling in nanosecond and should be kept as short as possible. The input capacitor needs not only to be close to the VIN pin, but also to the GND pin in order to reduce the IC supply ripple. [Figure 27](#) shows a sample layout.

10.2 Layout Example

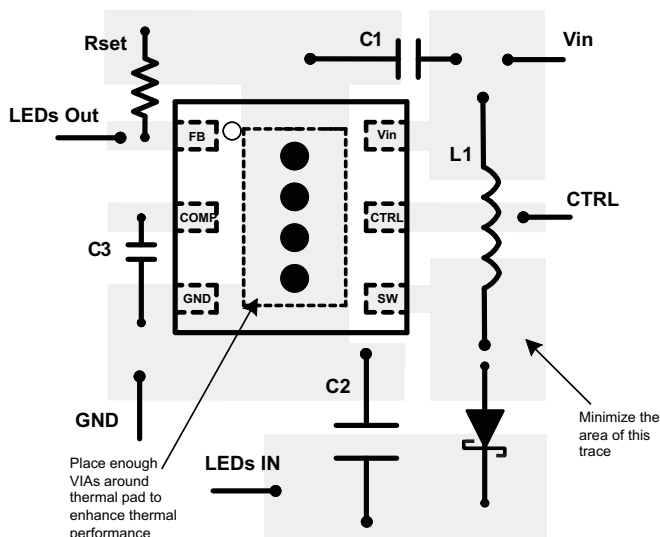


Figure 27. Sample Layout

10.3 Thermal Considerations

The maximum IC junction temperature should be restricted to 125°C under normal operating conditions. This restriction limits the power dissipation of the TPS61160A/61A. Calculate the maximum allowable dissipation, $P_{D(max)}$, and keep the actual dissipation less than or equal to $P_{D(max)}$. The maximum-power-dissipation limit is determined using [Equation 16](#):

$$P_{D(max)} = \frac{125^{\circ}\text{C} - T_A}{R_{\theta JA}}$$

where

- T_A is the maximum ambient temperature for the application.
- $R_{\theta JA}$ is the thermal resistance junction-to-ambient given in [Dissipation Ratings](#). (16)

The TPS61160A/61A comes in a thermally enhanced QFN package. This package includes a thermal pad that improves the thermal capabilities of the package. The $R_{\theta JA}$ of the QFN package greatly depends on the PCB layout and thermal pad connection. The thermal pad must be soldered to the analog ground on the PCB. Using thermal vias underneath the thermal pad as illustrated in the layout example. Also see the [QFN/SO8 PCB Attachment](#) application report ([SLUA271](#)).

11 Device and Documentation Support

11.1 Device Support

11.1.1 Third-Party Products Disclaimer

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11.2 Documentation Support

11.2.1 Related Documentation

For related documentation, see the following application reports:

QFN/SON PCB Attachment ([SLUA271](#)).

How to Use Analog Dimming With the TPS6116x ([SLVA471](#)).

Design Tool for Analog Dimming Using a PWM Signal (<http://www.ti.com/lit/zip/slvc366>).

11.3 Related Links

[Table 3](#) below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 3. Related Links

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
TPS61160A	Click here	Click here	Click here	Click here	Click here
TPS61161A	Click here	Click here	Click here	Click here	Click here

11.4 Trademarks

All trademarks are the property of their respective owners.

11.5 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

11.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TPS61160ADRVR	ACTIVE	SON	DRV	6	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	OBV	Samples
TPS61160ADRVT	ACTIVE	SON	DRV	6	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	OBV	Samples
TPS61161ADRVR	ACTIVE	SON	DRV	6	3000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	OBT	Samples
TPS61161ADRVT	ACTIVE	SON	DRV	6	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	-40 to 85	OBT	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSELETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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TAPE AND REEL INFORMATION

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS61160ADRVR	SON	DRV	6	3000	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2
TPS61160ADRVT	SON	DRV	6	250	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2
TPS61161ADRVR	SON	DRV	6	3000	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2
TPS61161ADRVT	SON	DRV	6	250	179.0	8.4	2.2	2.2	1.2	4.0	8.0	Q2
TPS61161ADRVT	SON	DRV	6	250	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2

TAPE AND REEL BOX DIMENSIONS

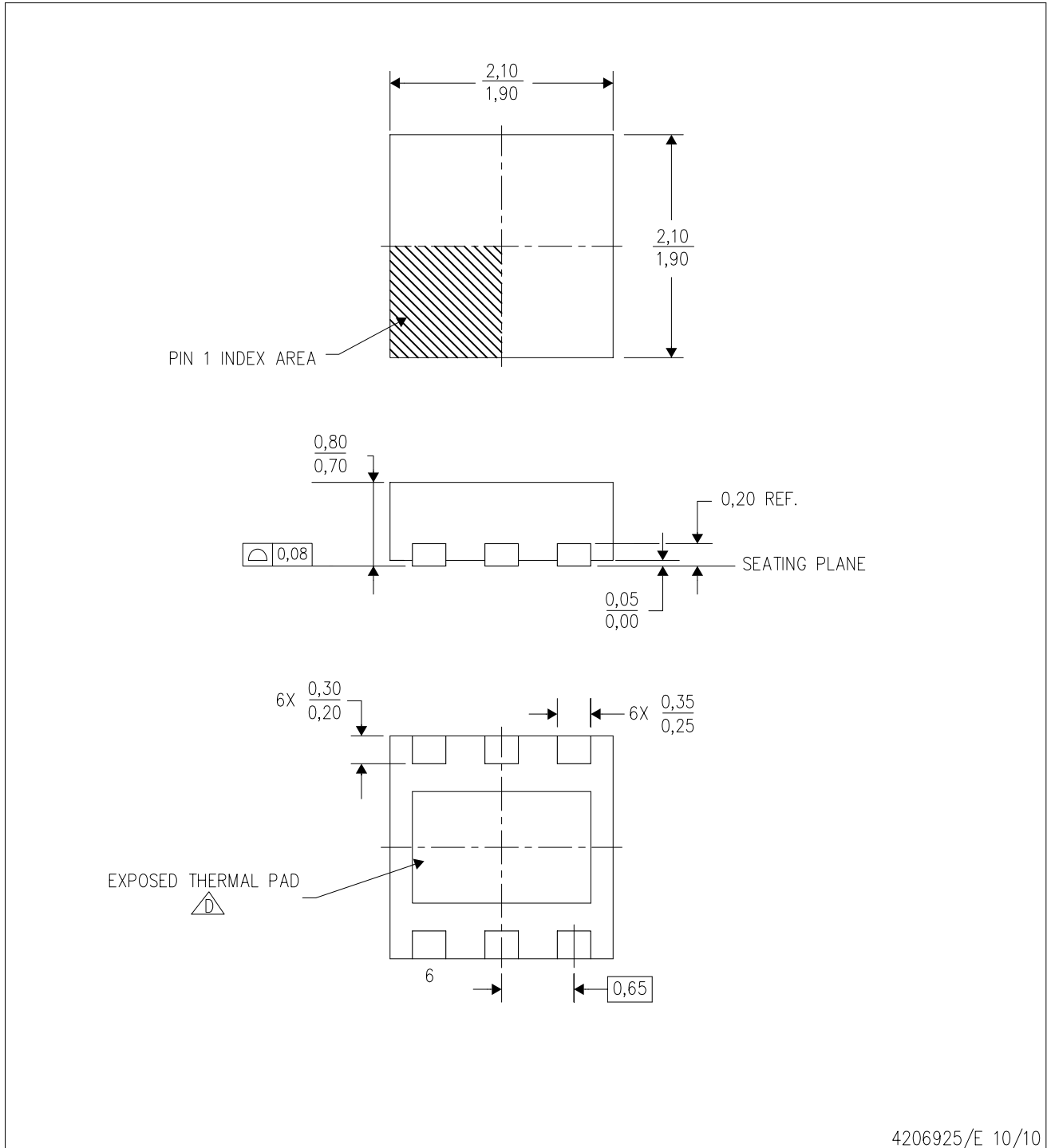

*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS61160ADRV	SON	DRV	6	3000	210.0	185.0	35.0
TPS61160ADRV	SON	DRV	6	250	210.0	185.0	35.0
TPS61161ADRV	SON	DRV	6	3000	210.0	185.0	35.0
TPS61161ADRV	SON	DRV	6	250	195.0	200.0	45.0
TPS61161ADRV	SON	DRV	6	250	210.0	185.0	35.0

MECHANICAL DATA

DRV (S-PWSON-N6)

PLASTIC SMALL OUTLINE NO-LEAD



4206925/E 10/10

- NOTES:
- All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
 - This drawing is subject to change without notice.
 - Small Outline No-Lead (SON) package configuration.
- $\triangle D$ The package thermal pad must be soldered to the board for thermal and mechanical performance. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.

THERMAL PAD MECHANICAL DATA

DRV (S-PWSON-N6)

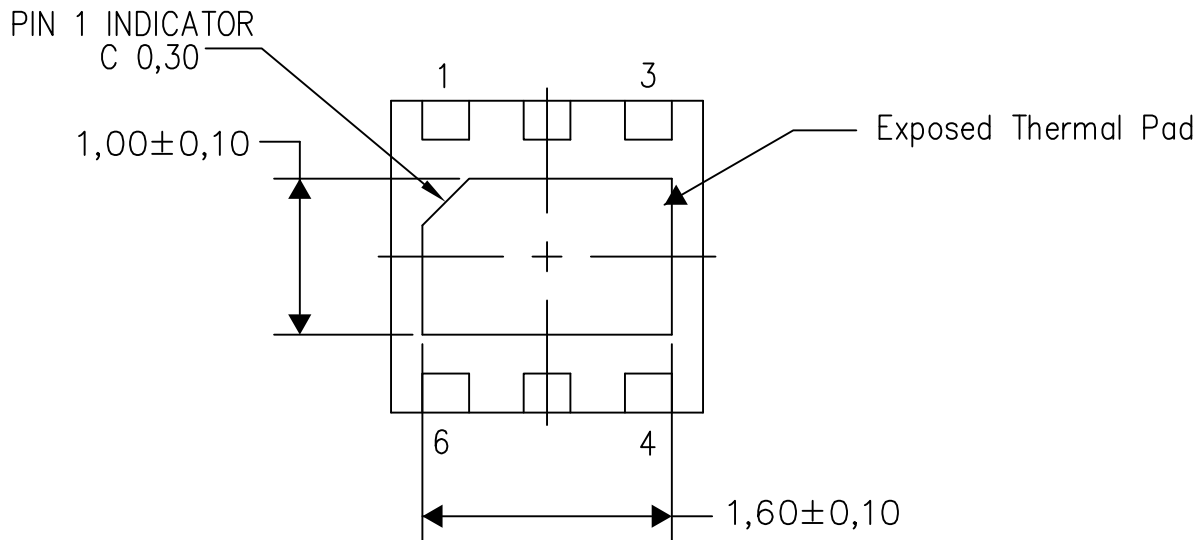
PLASTIC SMALL OUTLINE NO-LEAD

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



Bottom View

Exposed Thermal Pad Dimensions

4206926/Q 04/15

NOTE: All linear dimensions are in millimeters

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